

# Classification of DE's

DE:  $F(t, x, x^{(1)}, \dots, x^{(k)}) = 0$

$$x^{(j)}(t) = \frac{d^j x}{dt^j}(t) \quad j \in \mathbb{N}_0 = \{0, 1, 2, \dots\}$$

t indep var      solve for  $x \in C^k(J)$        $J \subseteq \mathbb{R}$   
 x dep. var  
 k order

~~Solution~~: F a function of  $k+2$  vars on some set  $U$   
 $U \subset \mathbb{R}^{k+2}$

Sol. on interval  $I \subset J$  :

A function  $\psi(t)$  so

$$F(t, \psi(t), \psi'(t), \dots, \psi^{(k)}(t)) = 0$$

$\forall t \in I$

std form "solve" for  $x^{(k)}$

$$x^{(k)} = f(t, x, x^{(1)}, \dots, x^{(k-1)})$$

(solving for  $(t, y) \in U$  can be done locally

if  $\frac{\partial F}{\partial x^{(k)}} \neq 0$  at  $(t, y)$ )

by implicit function theorem

DE is linear if

$$f(t, y_0, y_1, \dots, y_{k-1}) = f(t, y)$$

is of the form  $g(t) + l(t, y)$

where  $l$  is linear in  $y$

$$\text{i.e. } \cancel{f(t, \alpha x + \beta y)} \quad \cancel{f(t, \alpha x + \beta y)} = \cancel{f(t, \alpha x + \beta y)} \\ = \cancel{\alpha} \alpha l(t, x) + \beta l(t, y)$$

i.e.  $f$  is of the form

$$f(t, y) = a_0(t)y_0 + a_1(t)y_1 + \dots + a_k(t)y_k$$

linear DE is autonomous if  $g(t) \equiv 0$

(nonlin:  ~~$f(t, y)$~~  is a function of  $y$  above)

ex

$$\frac{d^2 y}{dx^2} + x \frac{dy}{dx} + \sin x = 2$$

$$\frac{d^2 y}{dx^2} + \sin^2 x = 0$$

$$\frac{d^2 y}{dx^2} + \sin^2 y = 0$$

# Systems

ex  $y''' = f(t, y)$

let  $v_1 = y$     $v_2 = y'$     $v_3 = y''$

$$\Rightarrow \frac{dv_3}{dt} = f(t, y) = f(t, v_1)$$

$$\frac{dv_2}{dt} = v_3$$

$$\frac{dv_1}{dt} = v_2$$

$$\frac{dv}{dt} = \begin{pmatrix} \frac{dv_1}{dt} \\ \frac{dv_2}{dt} \\ \frac{dv_3}{dt} \end{pmatrix} = \begin{pmatrix} f(t, v_1) \\ v_3 \\ f(t, y) \end{pmatrix}$$


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General system:

$$\frac{dv}{dt} = \begin{pmatrix} f_1(t, v) \\ f_2(t, v) \\ \vdots \\ f_n(t, v) \end{pmatrix}$$

is linear if

$$f_i(t, v) = g_i(t) + \mathcal{L}_i(t, v)$$

where  $\mathcal{L}_i$  is linear in  $v$

(std form)

Any nth order DE can be ~~be~~ converted to 1st order form

ex  $\frac{d^n x}{dt^n} = f(t, x, x', \dots, x^{(n-1)})$

$y_1 = x \quad y_2 = x' \quad \dots \quad y_n = x^{(n-1)}$   
 $y_1' = y_2 \quad y_2' = y_3 \quad \dots \quad y_{n-1}' = y_n$

$y_n' = f(t, y_1, y_2, \dots, y_n)$   
 $= f(t, y)$

$\frac{dy}{dt} = \begin{pmatrix} f(t, y) \\ y_2 \\ y_3 \\ \vdots \\ y_n \\ f(t, y) \end{pmatrix} = F(t, y)$

$\frac{dy}{dt} = F(t, y)$  linear if .

$F(t, y) = G(t) = \underbrace{A(t)}_{n \times n} y$

Autonomous if F has no t dependence



Simplest case n=1

$\frac{dy}{dt} = F(t, y)$

Autonomous nonlin  $\frac{dy}{dt} = F(y)$

linear  $\frac{dy}{dt} = a(t)y + g(t)$

linear auton  $\frac{dy}{dt} = ay$

Convert nonauton. DE to auton. system: ex.  $\frac{dx}{dt} = t^2 \sin x$

$y_1 = x$   
 $y_2 = x'$   
 $y_3 = t$   
 $\frac{dy}{dt} = \begin{pmatrix} y_2 \\ y_2 \sin y_1 \\ 1 \end{pmatrix}$

$$\underline{ex} \quad \ddot{x} + t\dot{x} = x$$

$$\underline{ex} \quad \dot{x} = y \quad \dot{y} = -x$$


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Def 10

linear 1st order autonomus

$$\dot{x} = ax$$

system  $\frac{dx_1}{dt} = a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n$

⋮

$$\frac{dx_n}{dt} = a_{n1}x_1 + \dots + a_{nn}x_n$$

$$^n \quad \frac{dx}{dt} = Ax$$

$$\boxed{\dot{x} = ax} : \quad \dot{x} - ax = 0$$

$$e^{-at} \cdot x - e^{-at} x = 0$$

$$\frac{d}{dt} (e^{-at} x) = 0$$

$$e^{-at} x = C$$

⋮

Review DE:  $F(t, x, x^{(1)}, \dots, x^{(n)}) = 0$  nth order DE

std form  $x^{(n)}(t) = f(t, x, x^{(1)}, \dots, x^{(n-1)})$

ex  $F(t, a, b) = t^2 + a^2 - b^2$   $\frac{\partial F}{\partial b} = -2b$   
 $\Rightarrow t^2 + x^2 - (x')^2$

if  $(x') \neq 0$  can invert:  $(x')^2 = t^2 + x^2$   
 $x' = \pm \sqrt{x^2 + t^2}$

if  $(t_0, x_0, y_0) = (1, 0, 1)$   
local inverse exists

$$x' = \sqrt{x^2 + t^2}$$

near  $(1, 0, -1)$  would be

$$x' = -\sqrt{x^2 + t^2}$$

Sol. methods

sep. of vars eg.  $x' = x^2$

$$\Rightarrow \frac{dx}{dt} = x^2 \Rightarrow \frac{dx}{x^2} = dt$$

$$-\frac{1}{x^2} = t + C$$

~~int. factor~~ ex  $x' = ax$

~~int. factor~~ linear 1st order

# 1st order autonomous

$$\dot{x} = f(x) \quad x(0) = x_0 \quad f \in C(\mathbb{R})$$

Assume  $f'(x_0) \neq 0$  so  $f(x)$  is nonzero for  $|x-x_0|$  small enough

$$\frac{dx}{f(x)} = dt$$



$$\int_0^t \frac{dx}{f(x(s))} ds = t$$

~~Let  $F(x) = \int$~~

$$\underbrace{\int_{x_0}^x \frac{dx}{f(x)}}_{F(x)} = t \quad (F'(x) = \frac{1}{f(x)})$$

$\Rightarrow$  sol<sup>n</sup>  $x(t)$  satisfies

$$F(x(t)) = t, \quad f(x_0) \neq 0 \Rightarrow F(x) \text{ monotone near } x_0$$

there is a unique inverse  $(F(x_0) = 0 \Rightarrow)$

$$x(t) = F^{-1}(t) \quad x(0) = F^{-1}(0) = x_0$$

If  $f(x) > 0 \Rightarrow f(x) > 0$  for  $x \in (x_1, x_2)$   
(interval contains  $x_0$ )

- pick this ~~max~~ as big as possible  
(maybe  $x_1 = -\infty, x_2 = \infty$ )

define  $T_+ = \lim_{x \rightarrow x_2} F(x) \in (0, \infty]$  (monotone, bad seq's converge)

$$T_- = \lim_{x \rightarrow x_1} F(x) \in [-\infty, 0)$$

then  $x \in C^1(T_-, T_+)$  and

$$\lim_{t \rightarrow T_+} x(t) = x_2, \quad \lim_{t \rightarrow T_-} x(t) = x_1$$

~~IF  $T_+ < \infty$  either  $x_2 = \infty$  or  $x_2 < \infty$~~

In particular,  $x$  is defined for all  $t > 0$  iff

$$T_+ = \int_{x_0}^{x_2} \frac{dy}{f(y)} = +\infty$$

i.e.  $\frac{1}{f(x)}$  not integrable near  $x_2$

likewise  $x$  defined for all  $t < 0$  iff

$\frac{1}{f(x)}$  not integrable near  $x_1$

Two cases if  $T_+ < \infty$

1)  $x_2 = \infty \Rightarrow x \text{ went to } \infty \text{ as } t \rightarrow T_+$

2)  $x_2 < \infty$

$$\lim_{t \rightarrow T_+} x(t) = x_2 < \infty$$

if  $f(x_2) > 0$  then  $x_2$  was not chosen maximally

if  $f(x_2) = 0$ , extend  $x(t)$  as a constant for  $t \geq T_+$  by setting  $x = x_2$

$$\text{in } \varphi(t) = \begin{cases} x(t) & t \leq T_+ \\ x_2 & t \geq T_+ \end{cases}$$

$$\varphi(t) = x_2 \text{ for } t \geq T_+ \text{ (since } \dot{x} = 0 \text{ for } t \geq T_+)$$

but extension could be non unique

ex  $\frac{dx}{dt} = 2\sqrt{|x|} \quad x(0) = 0$

$$\frac{dx}{\sqrt{|x|}} = 2 dt$$

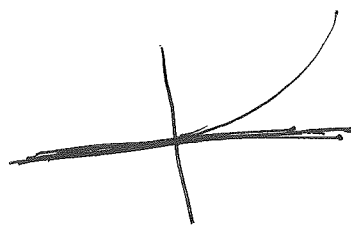
for  $x > 0$   $2x^{1/2}$

$$2x^{1/2} = 2t + C$$

$$x^{1/2} = t + K$$

$$x = (t + K)^2$$

$$x(0) = 0 \Rightarrow K = 0$$



next page do an example



what if  $f(x_0) = 0$ ?

$$\dot{x} = f(x), \quad x(0) = x_0$$

① Note  $\varphi(t) \equiv x_0$  is a solution:

$$\frac{d\varphi}{dt} \equiv 0, \quad f(x_0) = 0 \Rightarrow f(\varphi(t)) = 0$$

$$\varphi(0) = x_0 \quad \leftarrow$$

$$\text{If } \left| \int_{x_0}^{x_0+\varepsilon} \frac{dy}{f(y)} \right| < \infty$$

then there is another sol

$$\varphi(t) = F^{-1}(t), \quad F(x) = \int_{x_0}^x \frac{dy}{f(y)}$$

$$\text{with } \varphi(0) = F^{-1}(0)$$

$= x_0$  different from  $\varphi$   
constant sol.

HW 7 1.6, 1.7, 1.8, ~~1.12~~ 1.12 (iii)

For  $\dot{x} = x(t-x)$  ~~and~~  $x(0) = x_0$

Find  $(x_1, x_2)$  and  $(T_-, T_+)$  for all possible values of  $x_0$ .

~~Solve~~ The soln by separation of vars

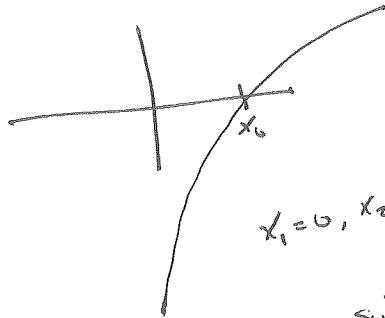
ex

f(x) = x x\_0 > 0

x\_1 = 0, x\_2 = \infty

1.8

F(x) = \int\_{x\_0}^x \frac{dy}{y} = \ln|y| \Big|\_{x\_0}^x = \ln(\frac{x}{x\_0}) = t



x\_1 = 0, x\_2 = \infty

~~positive on (x\_0, \infty)~~  
Note F monotonic

~~F is dy/dx finite~~

so T\_+ = \infty

as x \to \infty F(x) = t \to \infty  
as x \to 0 F(x) = t \to -\infty

solve for x

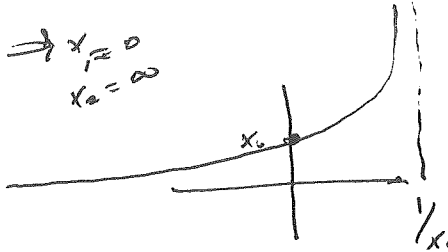
x = x\_0 e^t

- can show \phi is a rd. for all x \in \mathbb{R}

ex

f(x) = x^2 x\_0 > 0

\Rightarrow x\_1 = 0  
x\_2 = \infty



Sol. x(t) = \frac{x\_0}{1 - x\_0 t}

(T\_-, T\_+) = (-\infty, 1/x\_0)

F(x) = \int\_{x\_0}^x \frac{dy}{y^2} = \frac{1}{x\_0} - \frac{1}{x}

(x\_1, x\_2) = (0, \infty)

T\_+ = 1/x\_0 T\_- = -\infty

I = (-\infty, 1/x\_0)

ex

f(x) = 2\sqrt{|x|} x\_0 > 0

\infty x \to x\_1 = 0

F(x) \to -\infty = T\_-

\infty x \to x\_2 = \infty F(x) \to \frac{1}{x\_0}