

Problem Solving

Outline

I. Problem formulation

II. Example problems

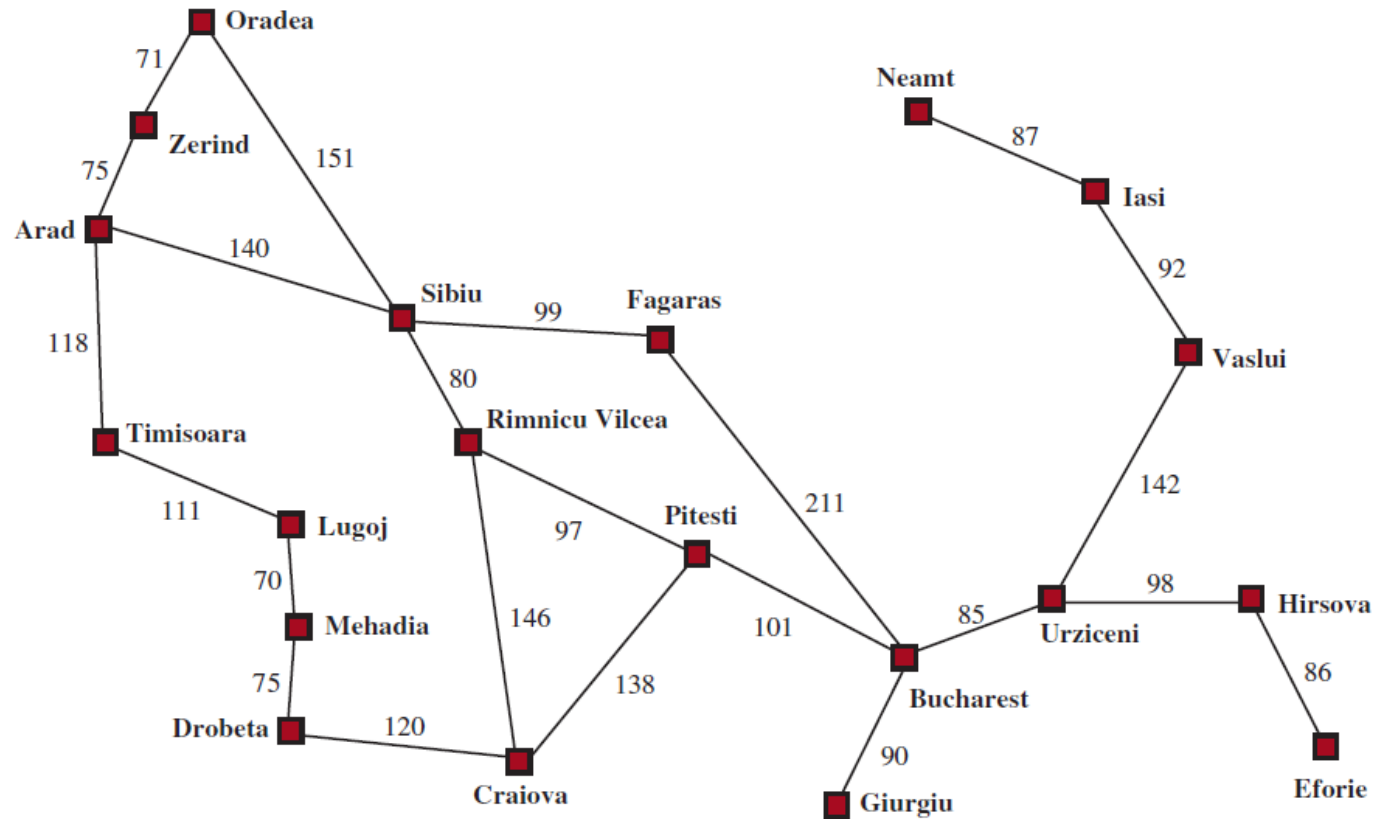
I. Problem-Solving Agent

- ♣ A reflex agent cannot operate when the mapping from states to actions becomes too large to store.

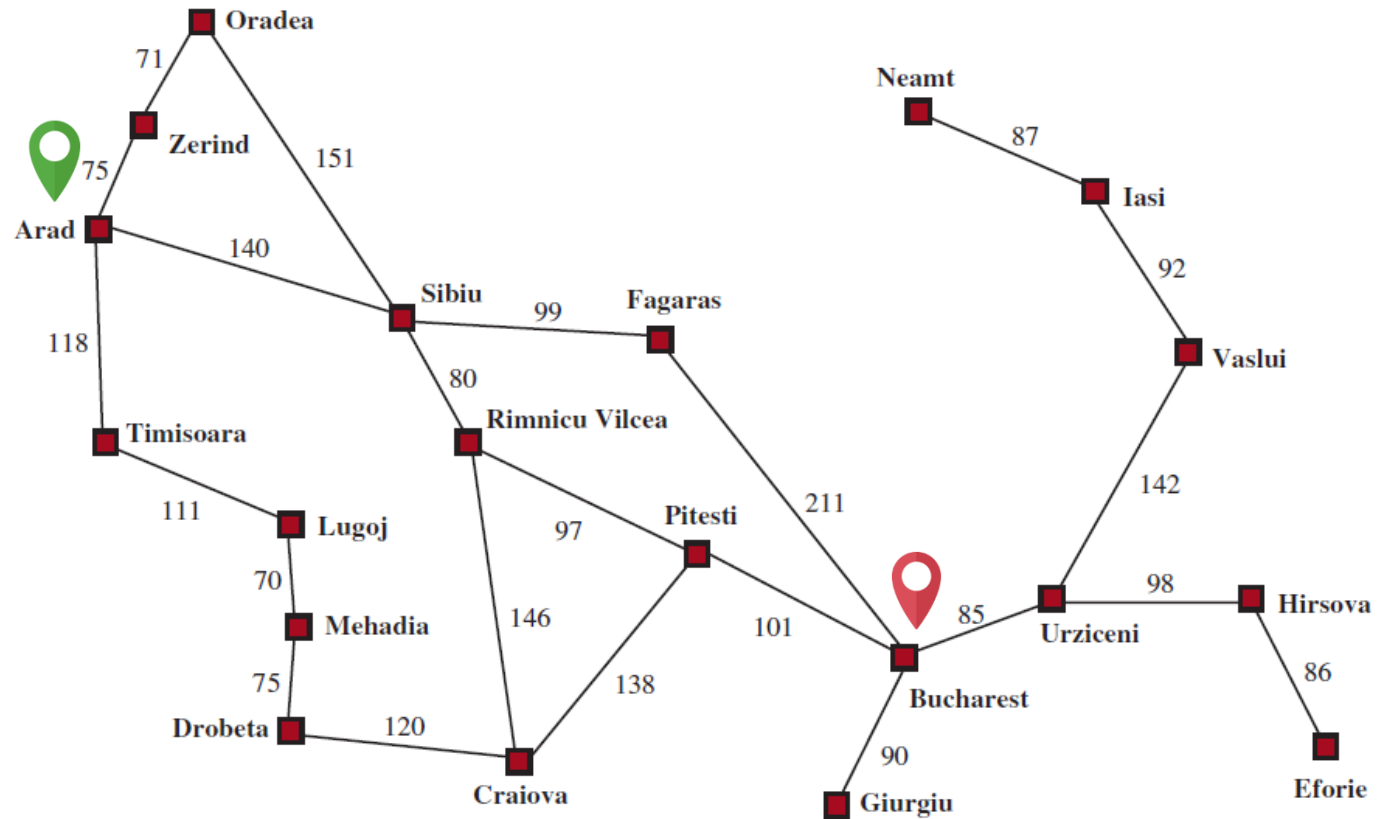
`if` current percepts `then` action

- A problem-solving agent is one kind of *goal-based* agent:
 - ◆ It considers states with no internal structure, i.e., in *atomic* representations.
- Problems are solved by general-purpose *search* algorithms.

Sightseeing Trip in Romania

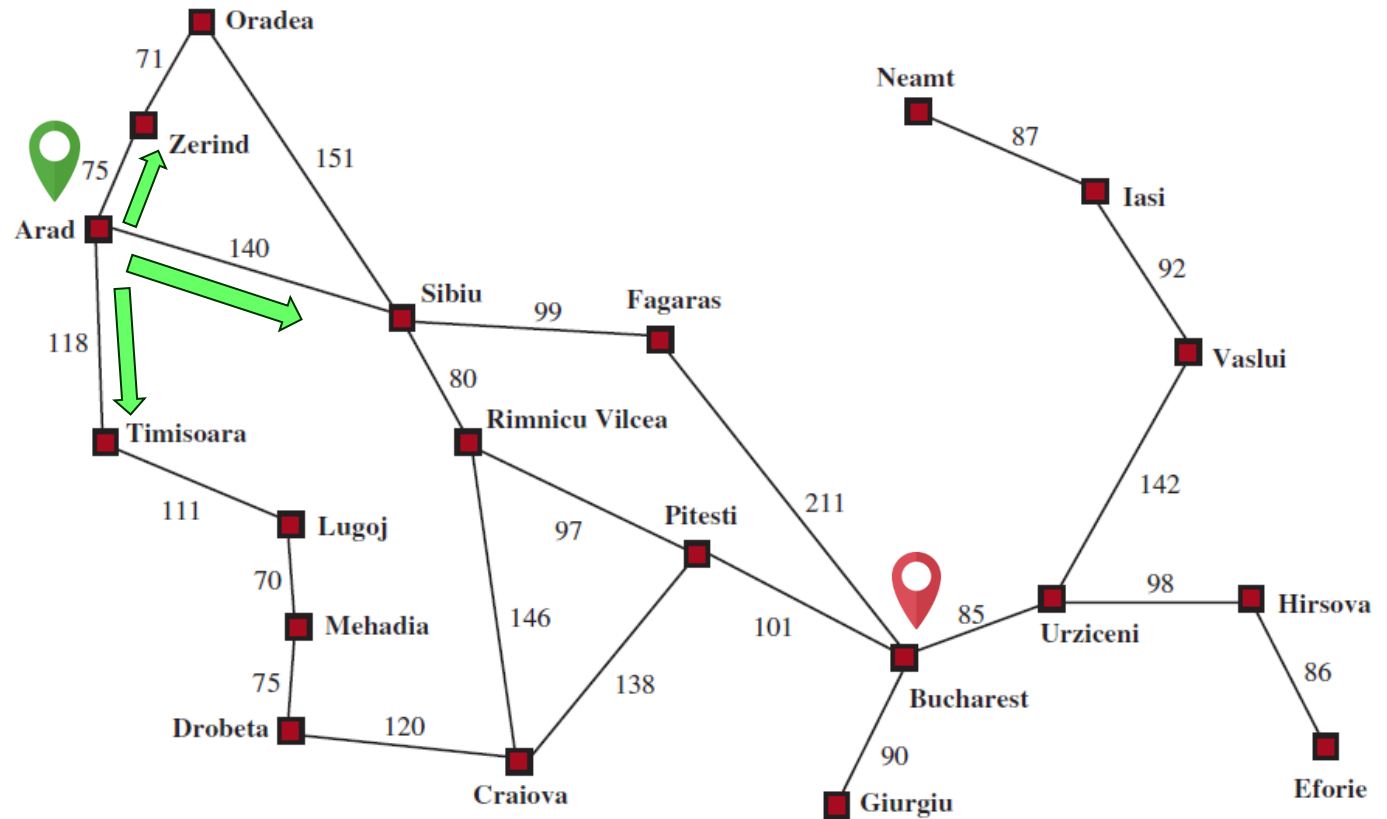


Sightseeing Trip in Romania



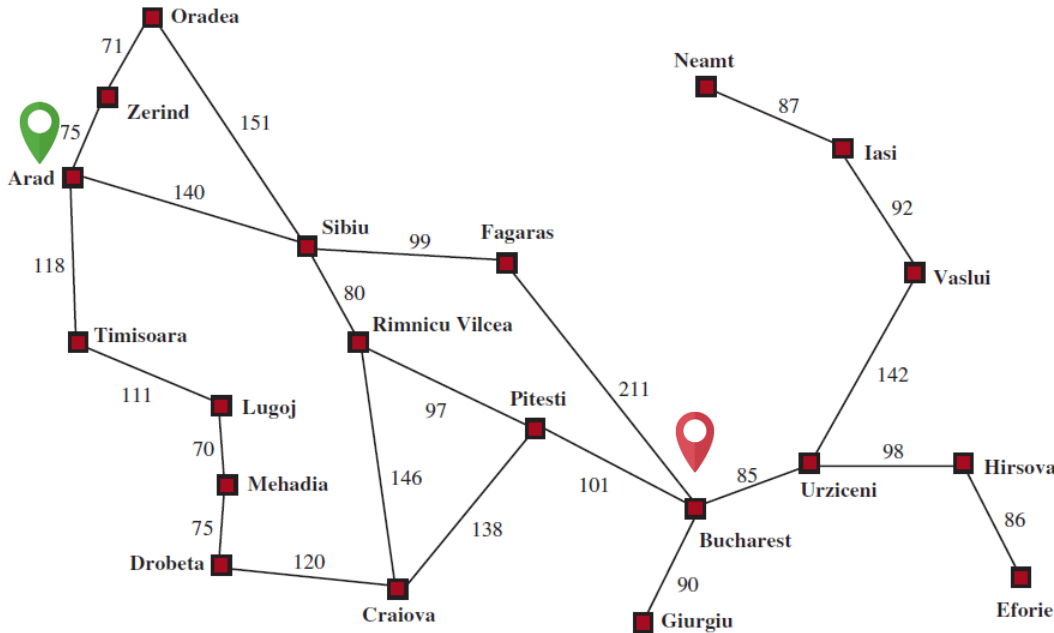
How to get to Bucharest from Arad?

Sightseeing Trip in Romania



How to get to Bucharest from Arad?

Four-Phase Problem Solving



◆ Goal formulation

◆ Problem formulation

states: cities

action: travel from one city to an adjacent city

◆ Search

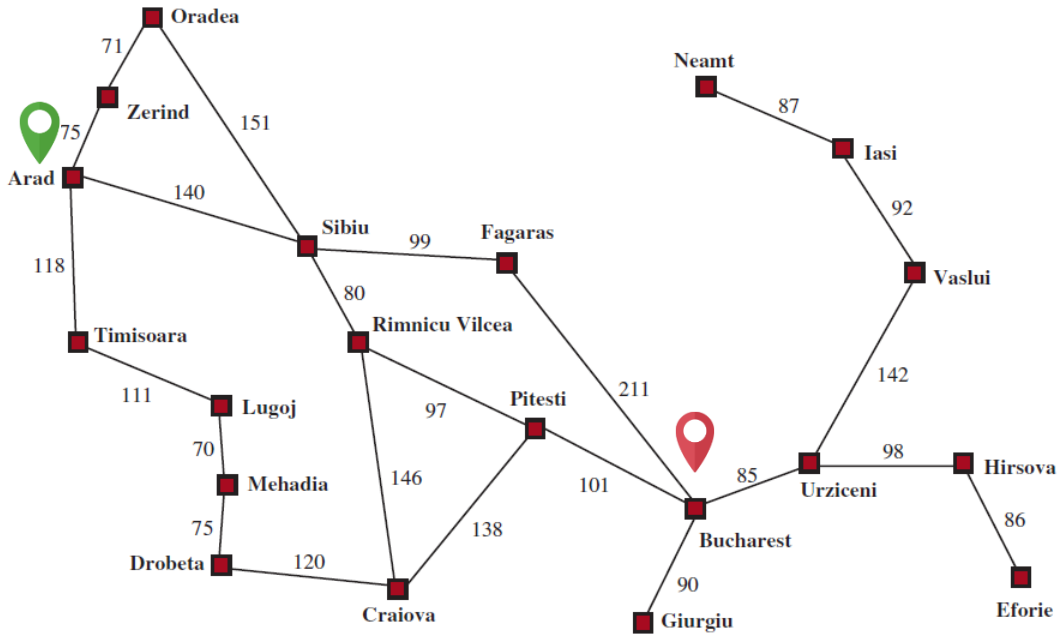
Find a solution.



A sequence of actions to reach the goal

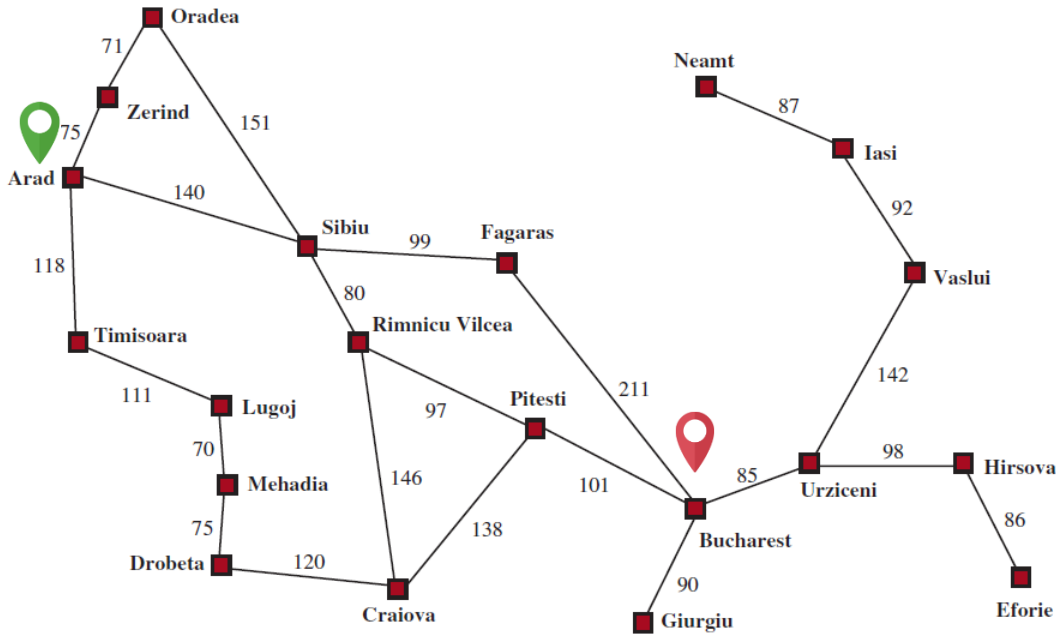
◆ Execution

Search Problem



◆ State space (as a graph)

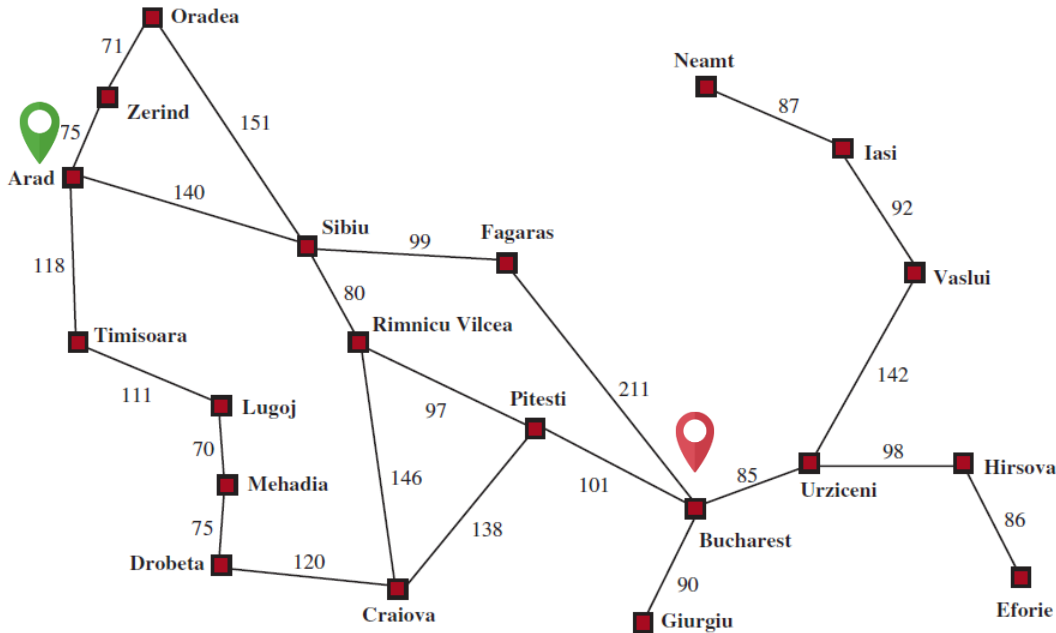
Search Problem



◆ State space (as a graph)

◆ Initial state (e.g., Arad)

Search Problem



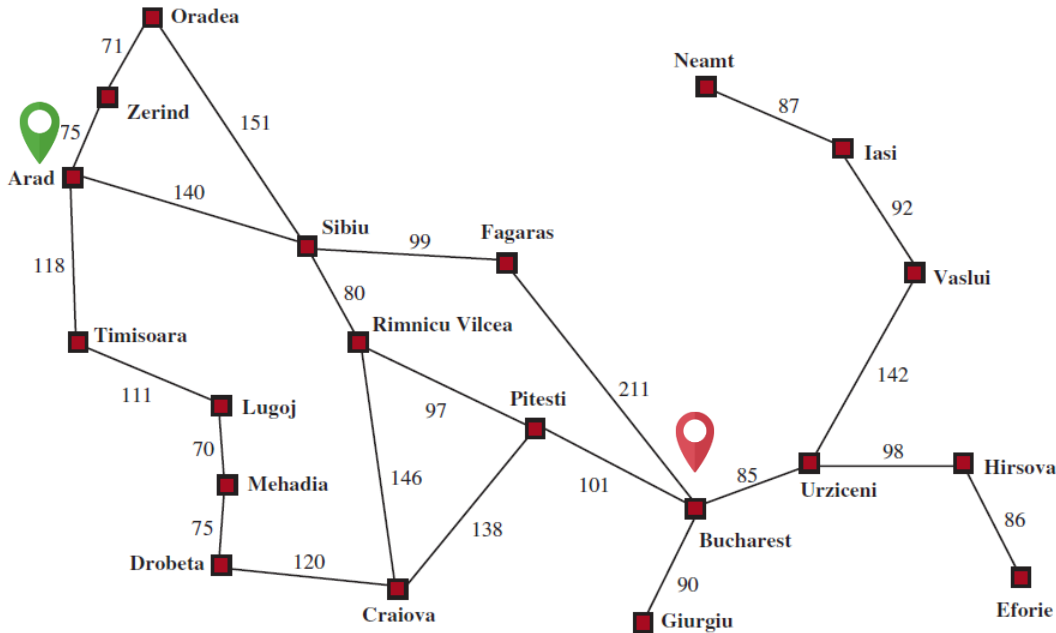
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◆ Goal state(s) (e.g., Bucharest)

IS-GOAL (Fagaras)

Search Problem



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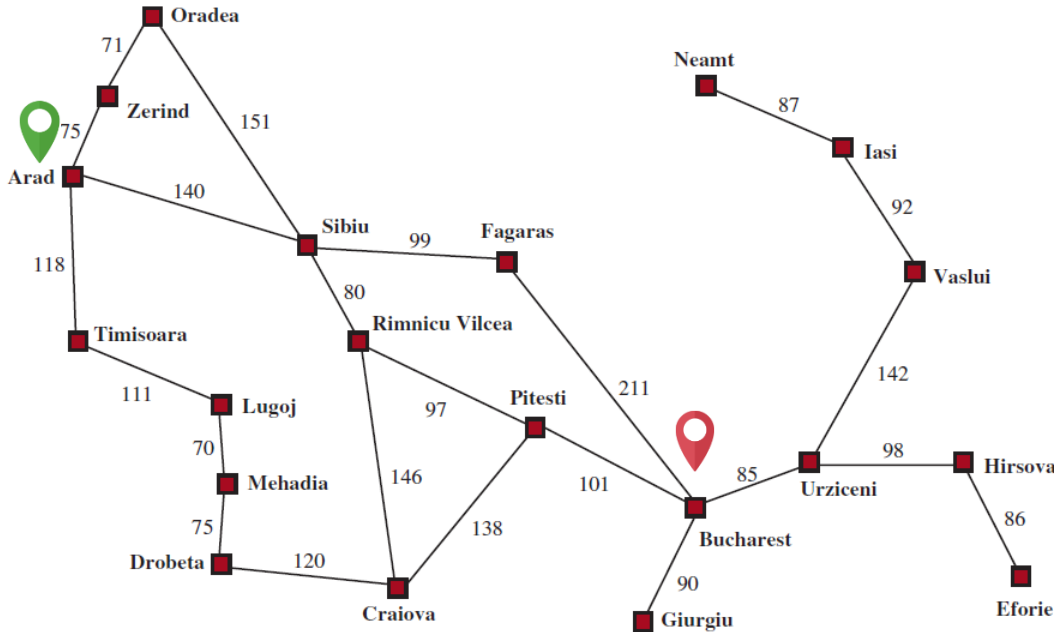
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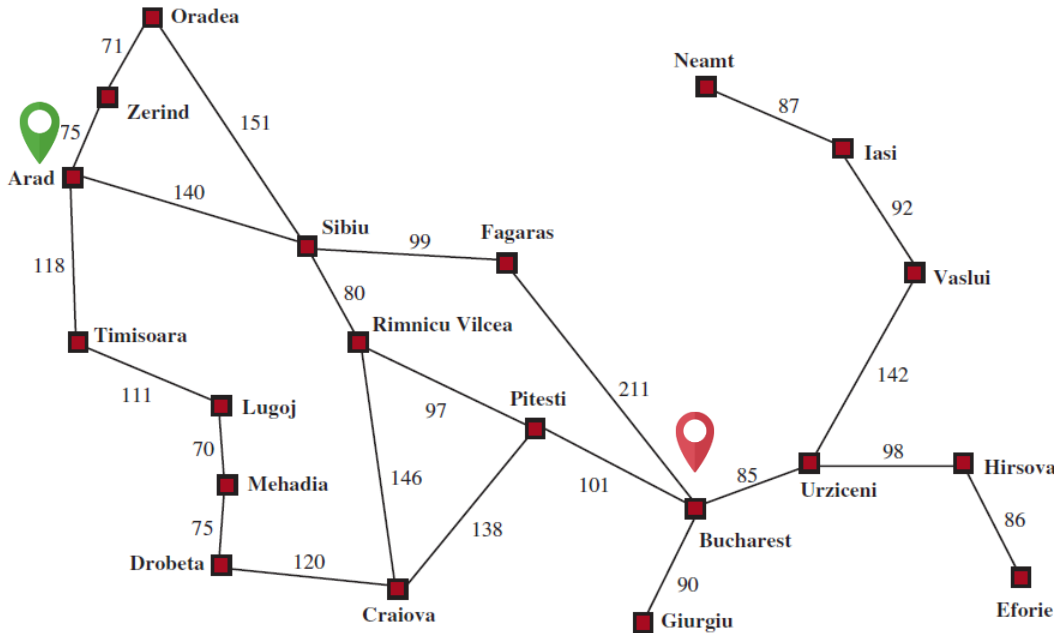
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$ACTIONS(s)$: a finite set of actions executable at state s .

$ACTIONS(Arad) = \{ToSibiu, ToTimisoara, ToZerind\}$

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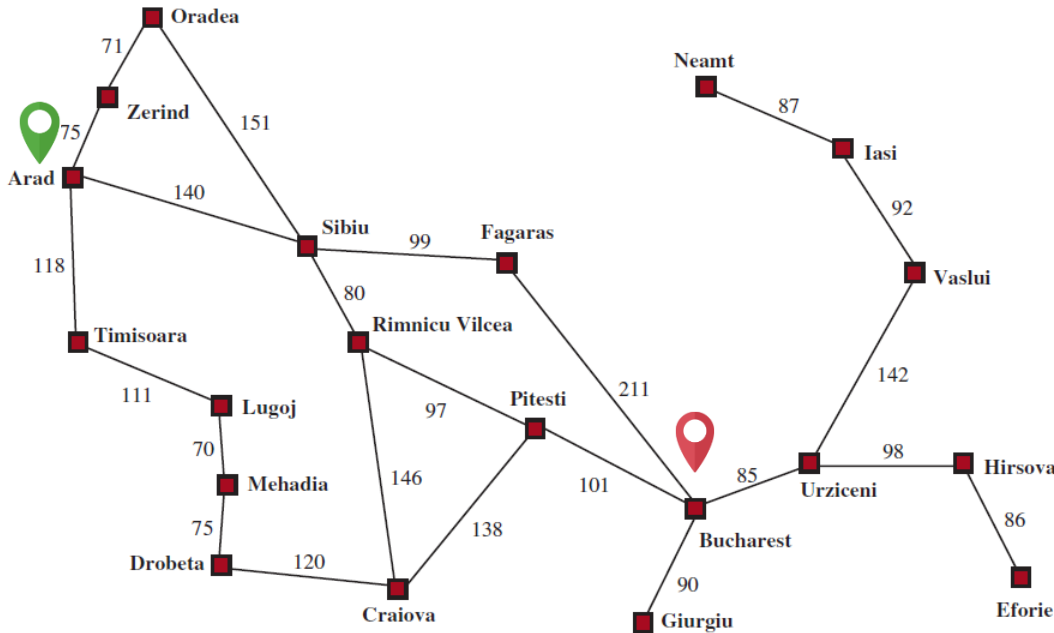
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$RESULT(Arad, ToZerind) = Zerind$

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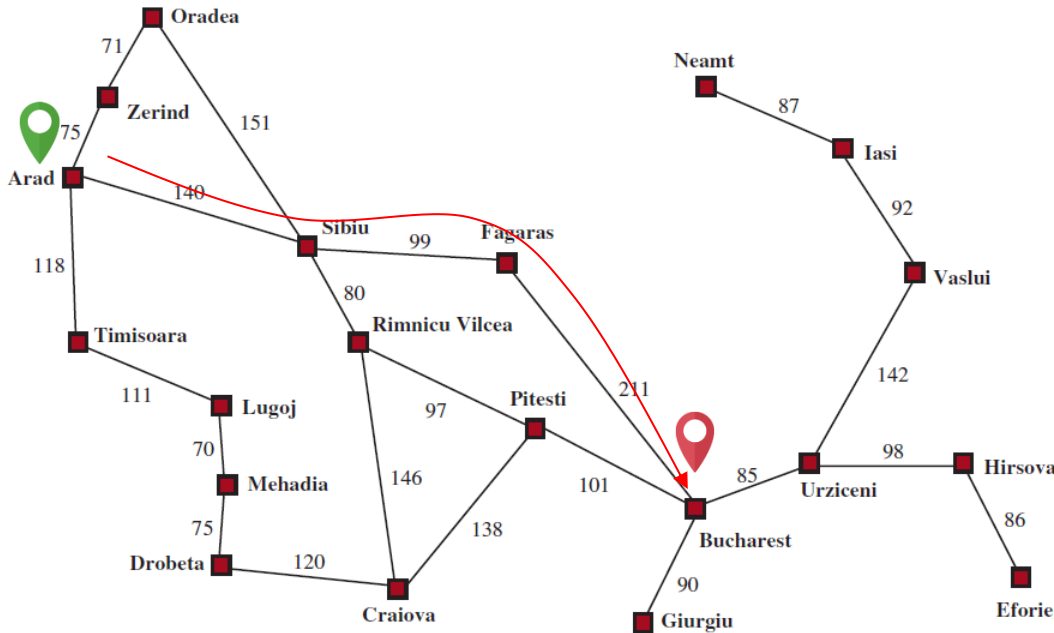
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$c(s, a, s')$: cost of applying action a in state s to reach state s' .

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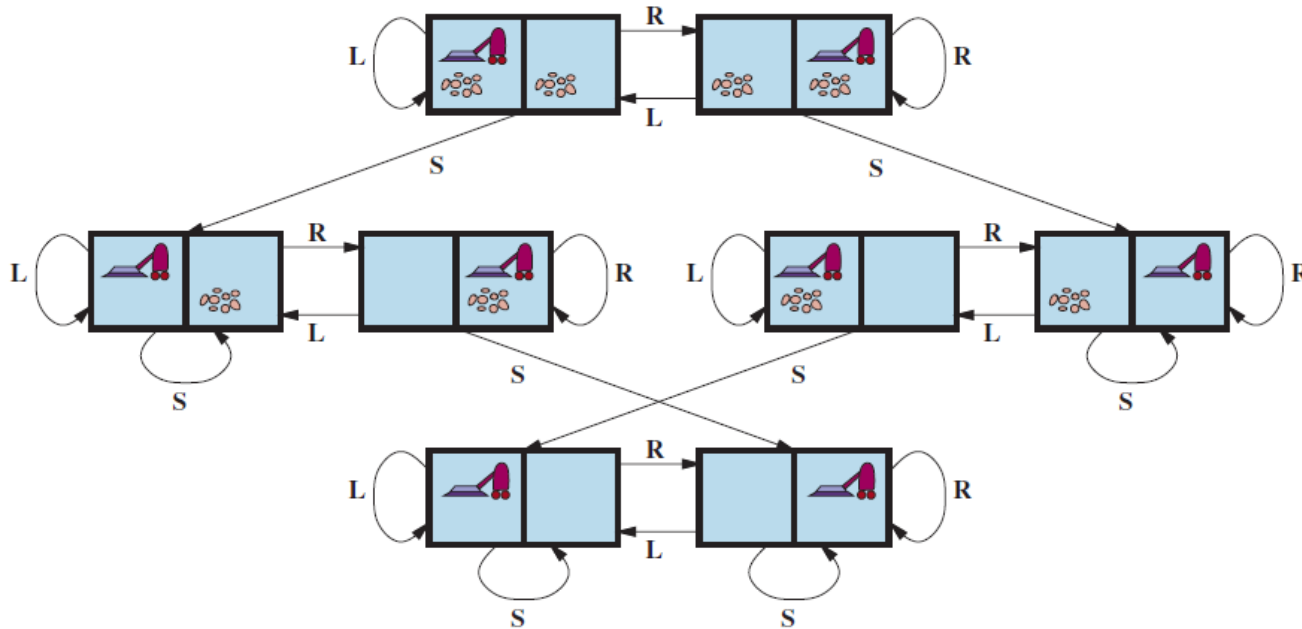
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◆ Solution: initial state \rightsquigarrow goal state (e.g., Arad – Sibiu – Fagaras – Bucharest)

II. Example 1: Vacuum World

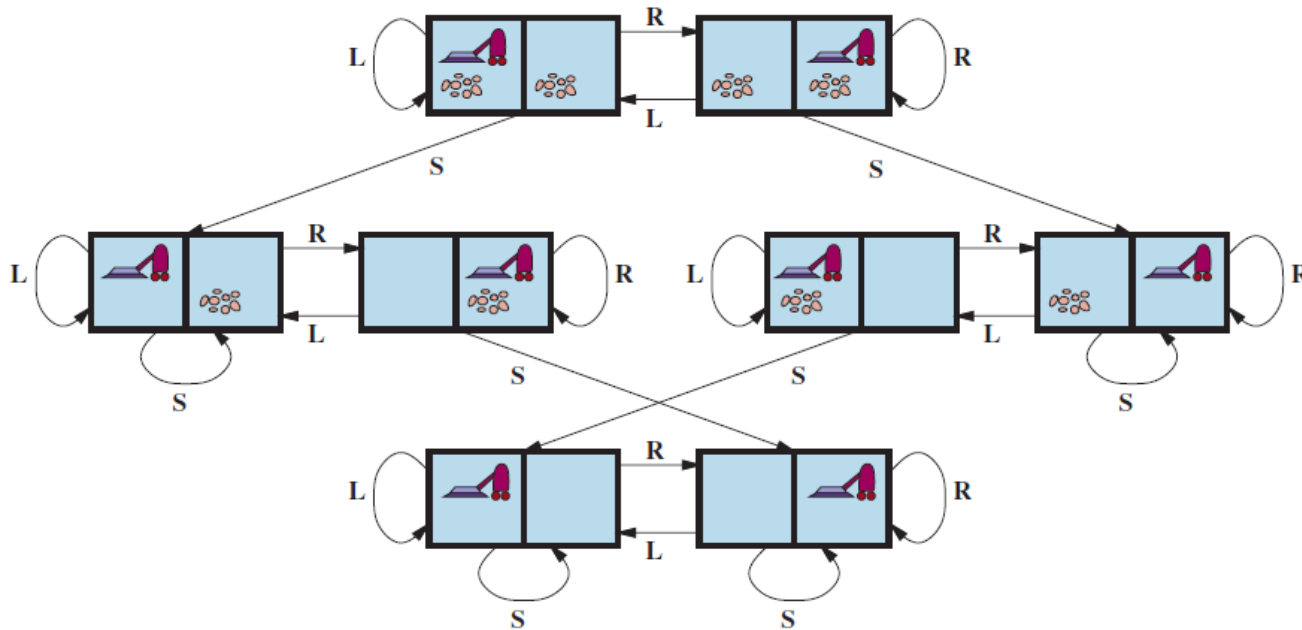
State-space graph:



- ◆ Actions: *Suck, Left, Right*
- ◆ Goal: every cell is clean.

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State-space graph:



Agent in either cell

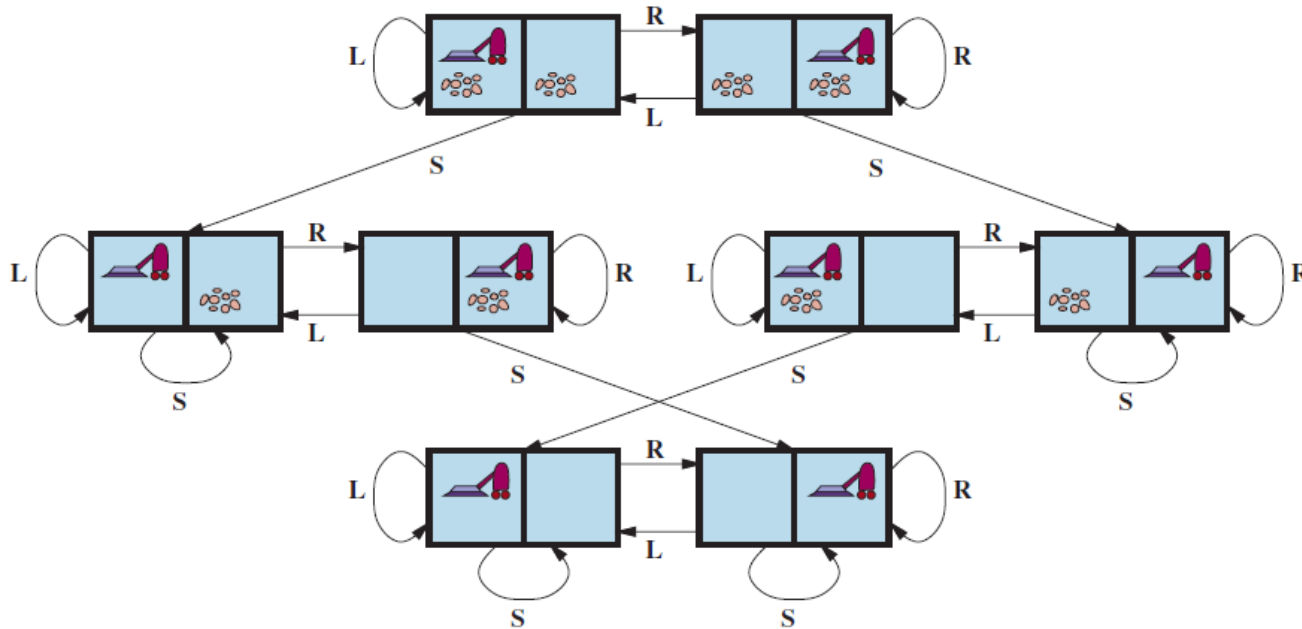


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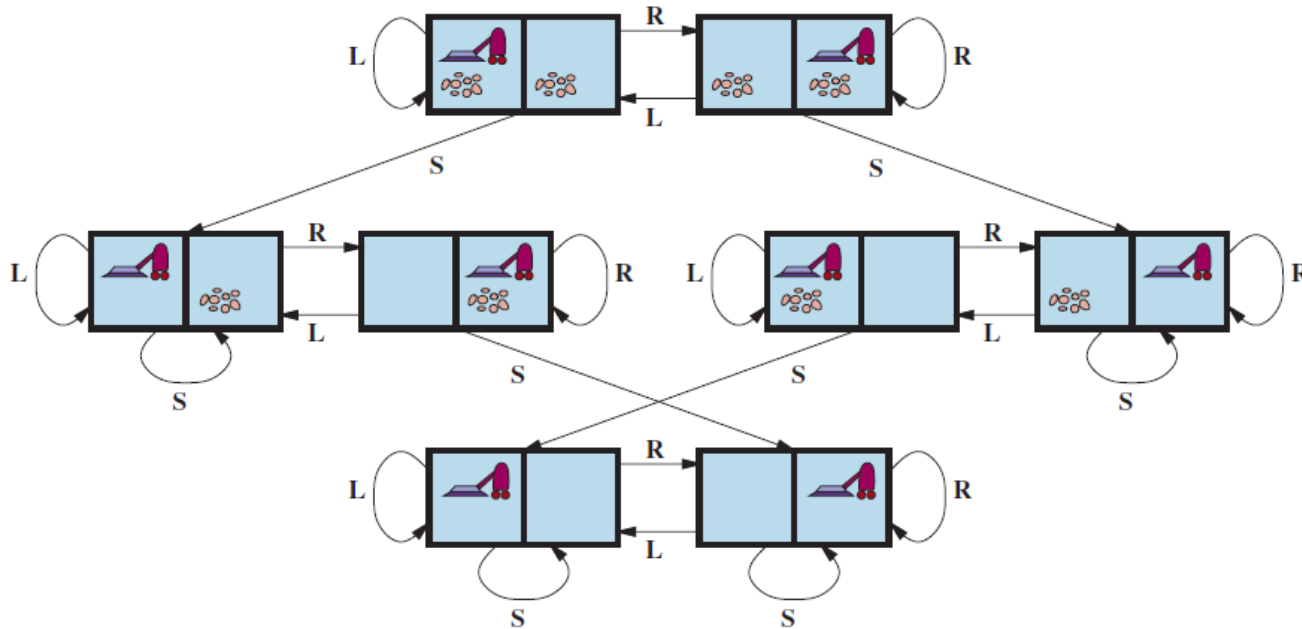
$$2 \cdot 2$$



Left cell has dirt or not

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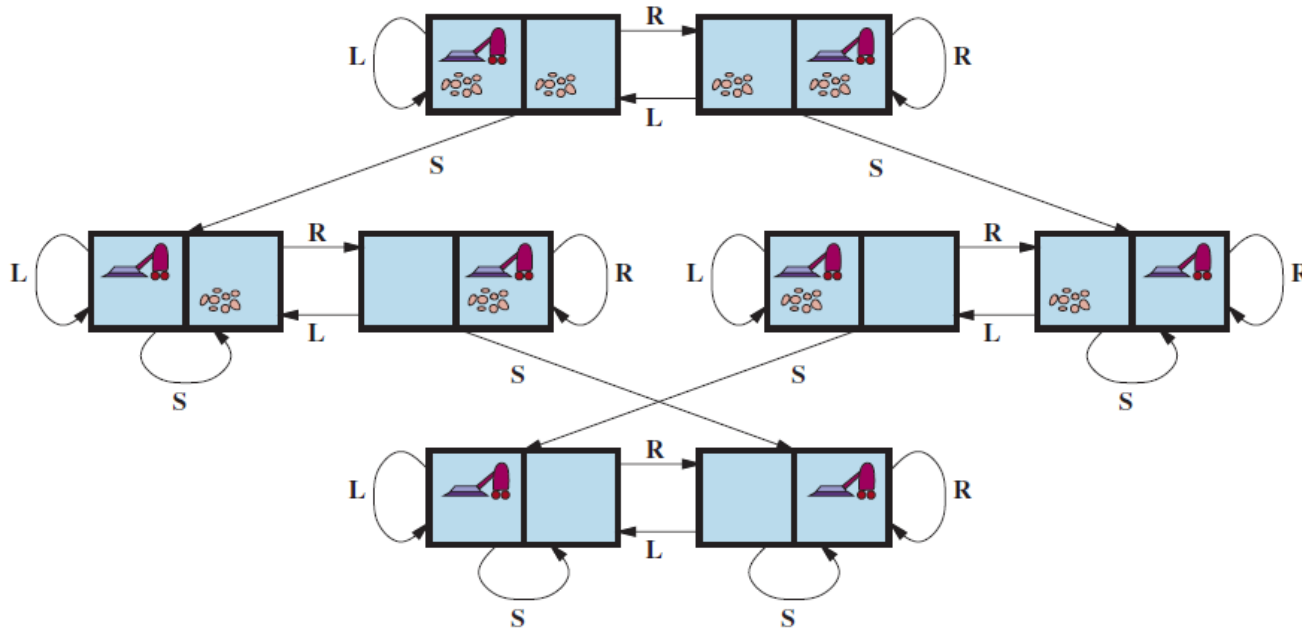
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- ◆ Cost: 1 for each action

Example 2: 8-Puzzle

1	2	3
6	5	7
8	4	

Initial state

1	2	3
8		4
7	6	5

Goal state

- ◆ Actions: ways of sliding a tile (adjacent to the blank space).

Left, Right, Up, Down

↑
Applied to the
right neighbor
of the blank space

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Solution to an 8-Puzzle

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Inversions in an 8-Puzzle

State in which all the tiles appear in the correct order.

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Every tile with a smaller number must be either above or, if in the same row, to the left of any tile with a larger number.

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Starting from the top, we scan the tiles row by row, and within each row, from left to right. Ignore the blank tile.

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- ◆ In the resulting sequence, every instance of a number appearing before a smaller one is counted as one inversion.

Counting Inversions

How many inversions are in the goal state?

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- 6 comes before 5
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7 inversions!

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(7 inversions)

If we fix the goal state at

1	2	3
8		4
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 the puzzle is solvable if and only if the initial state has an **odd** number of inversions.

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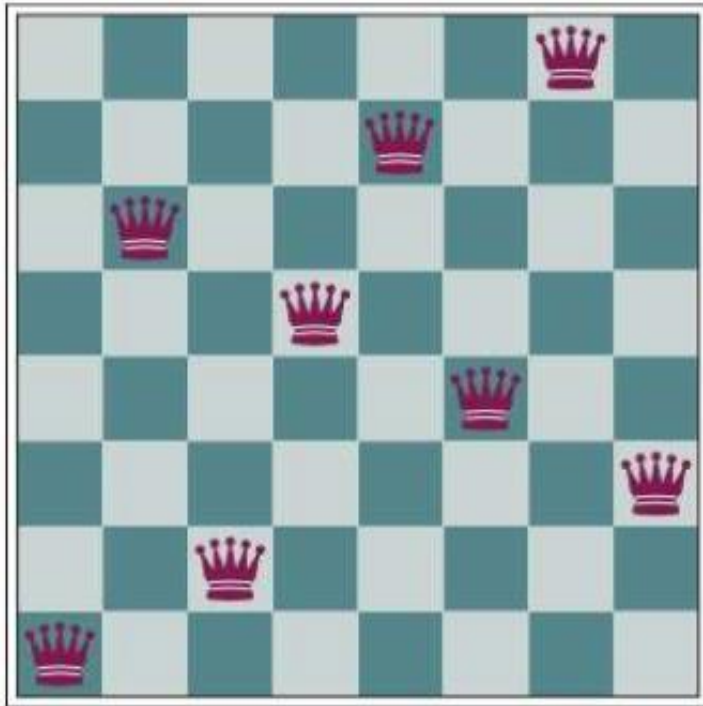
6 inversions: \Rightarrow Not solvable

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The 8-Queens Problem



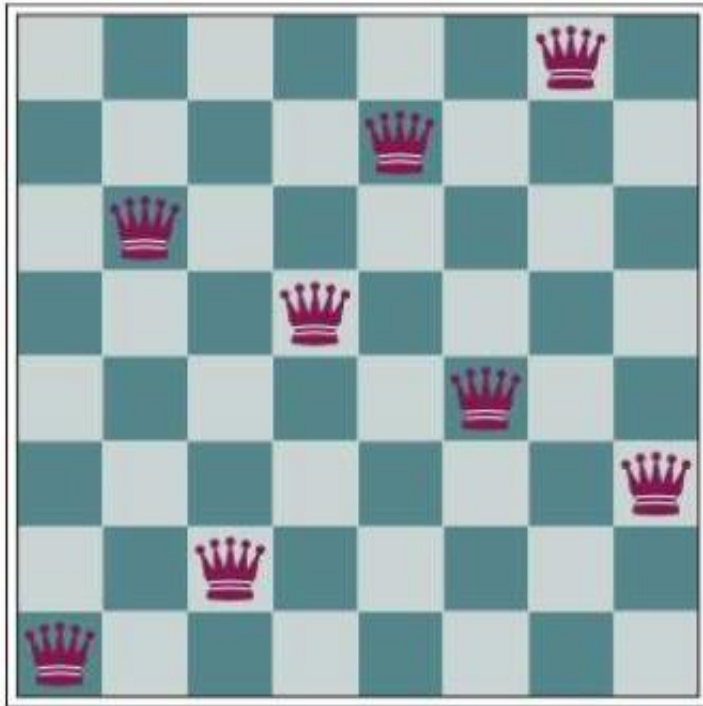
- ◆ Goal: A placement of 8 queens on the chess board in which no queen **attacks** another.



Same row, column, or diagonal

- ◆ Initial state: no queen on the board.

The 8-Queens Problem



Close to a solution

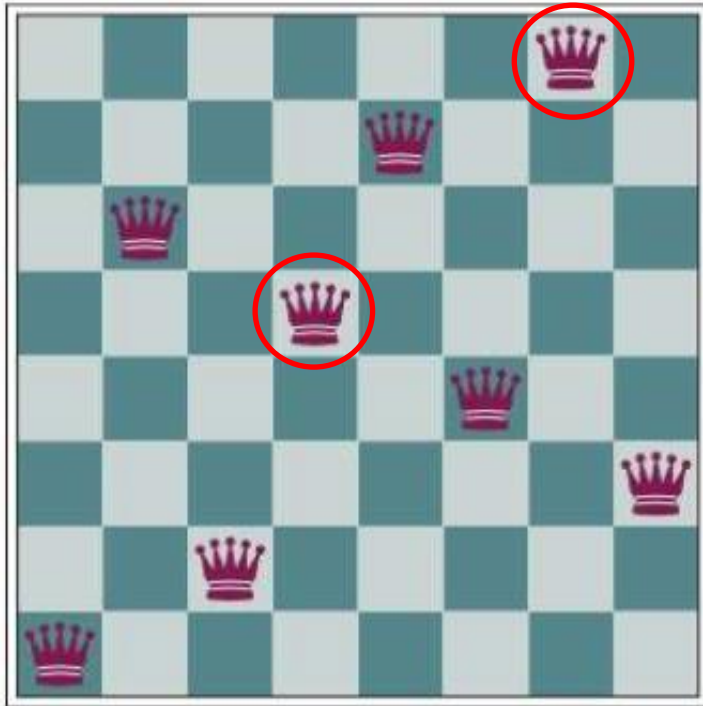
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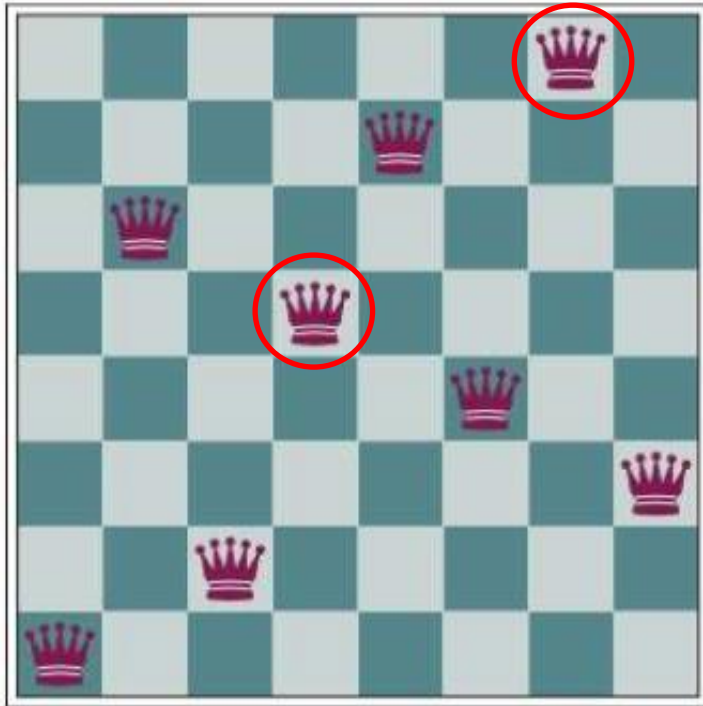
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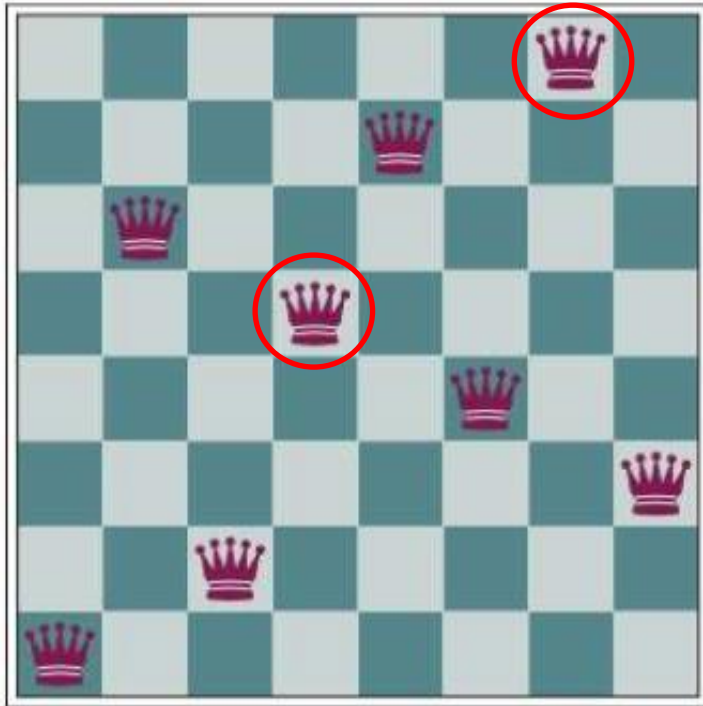


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The n -queens problem

Place n queens on an $n \times n$ chess board so that no queen attacks another.

Knuth's Conjecture (1964)



Donald Knuth (Stanford)
“father of the analysis of algorithms”
ACM Turing Award (1974)
National Medal of Science (1979)

Any integer > 4 can be reached from 4 via a sequence of square root, floor, and factorial operations.

$$\left\lfloor \sqrt{\sqrt{\sqrt{\sqrt{\sqrt{(4!)!}}}}} \right\rfloor = 5$$

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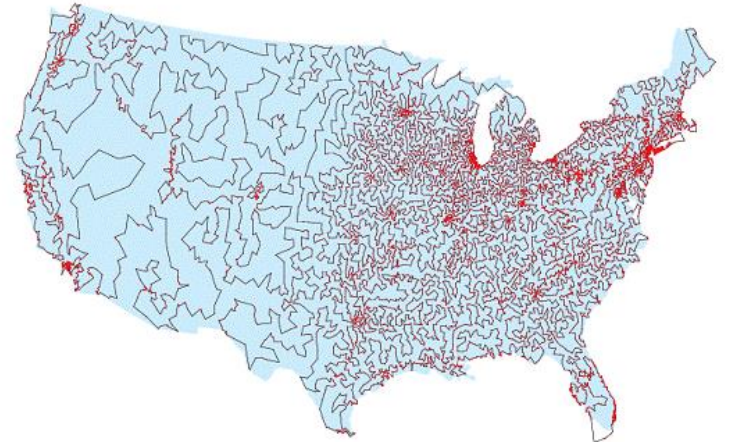
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- ◆ States: positive real numbers.
- ◆ Initial state: 4.
- ◆ Goal state: the desired integer > 4 .
- ◆ Actions: square root, floor, or factorial operation.
- ◆ Action cost: 1.

Real-World Problems

- Route finding (e.g., from Ames, IA to Mountain View, CA)
- Traveling salesman problem



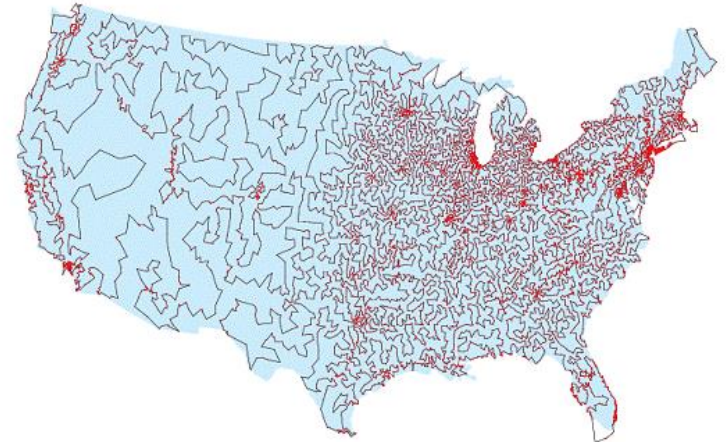
Round trip visiting 13,509 US cities
with population size > 500 exactly once*

* Figure from http://www.crpc.rice.edu/CRPC/newsletters/sum98/news_tsp.html.

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- VLSI layout

Positioning of millions of components and connections on a chip.

- Robot navigation

- Autonomous assembly sequencing (e.g., protein design)

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