

Computational Geometry

The systematic study of algorithms and data structures for geometric objects, with a focus on exact algorithms that are asymptotically fast.

Two key ingredients of a good algorithmic solution:

- ◆ Thorough understanding of the problem geometry
- ◆ Proper application of algorithmic techniques and data structures

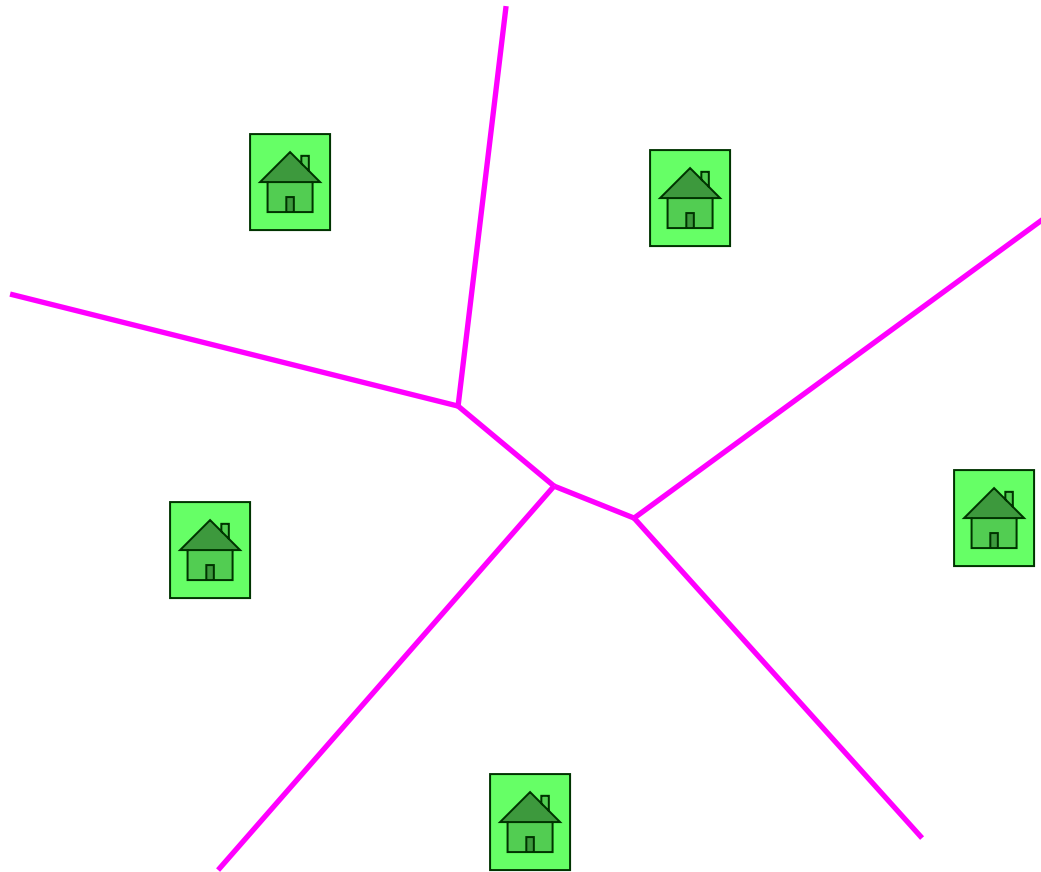
Example 1 – Proximity

Closest café on campus?



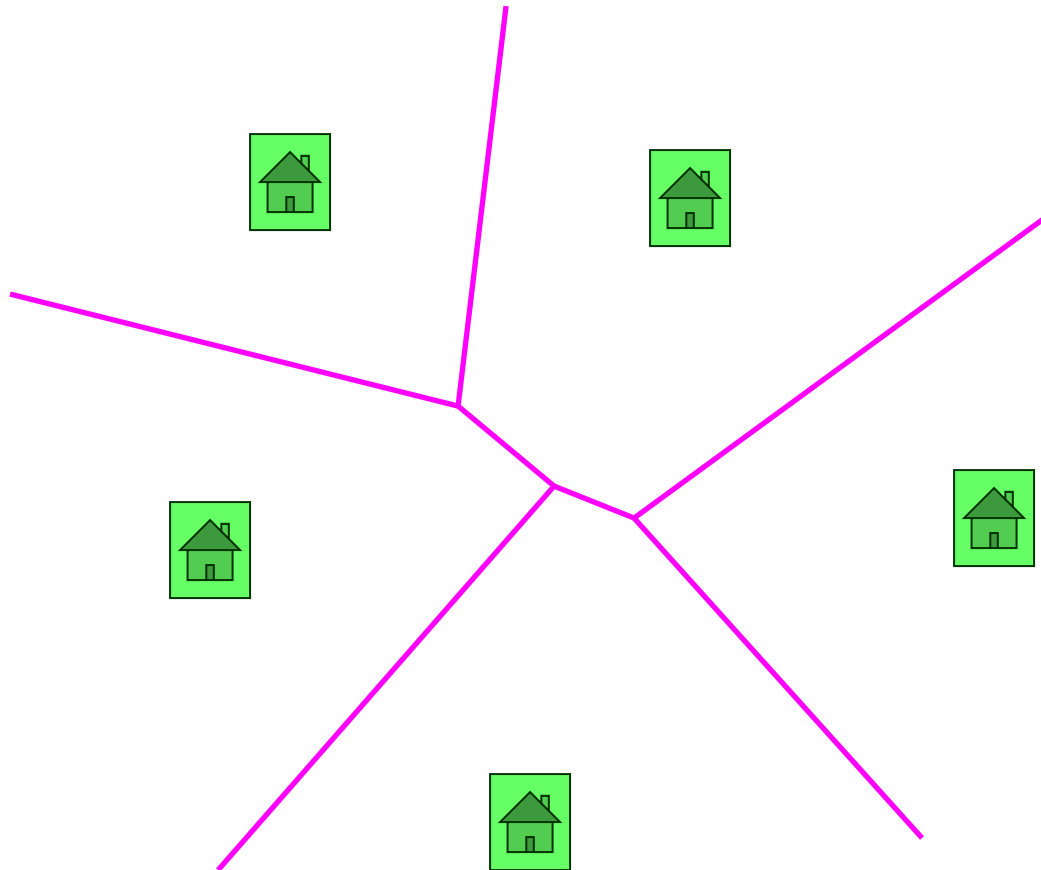
Example 1 – Proximity

Closest café on campus?



Example 1 – Proximity

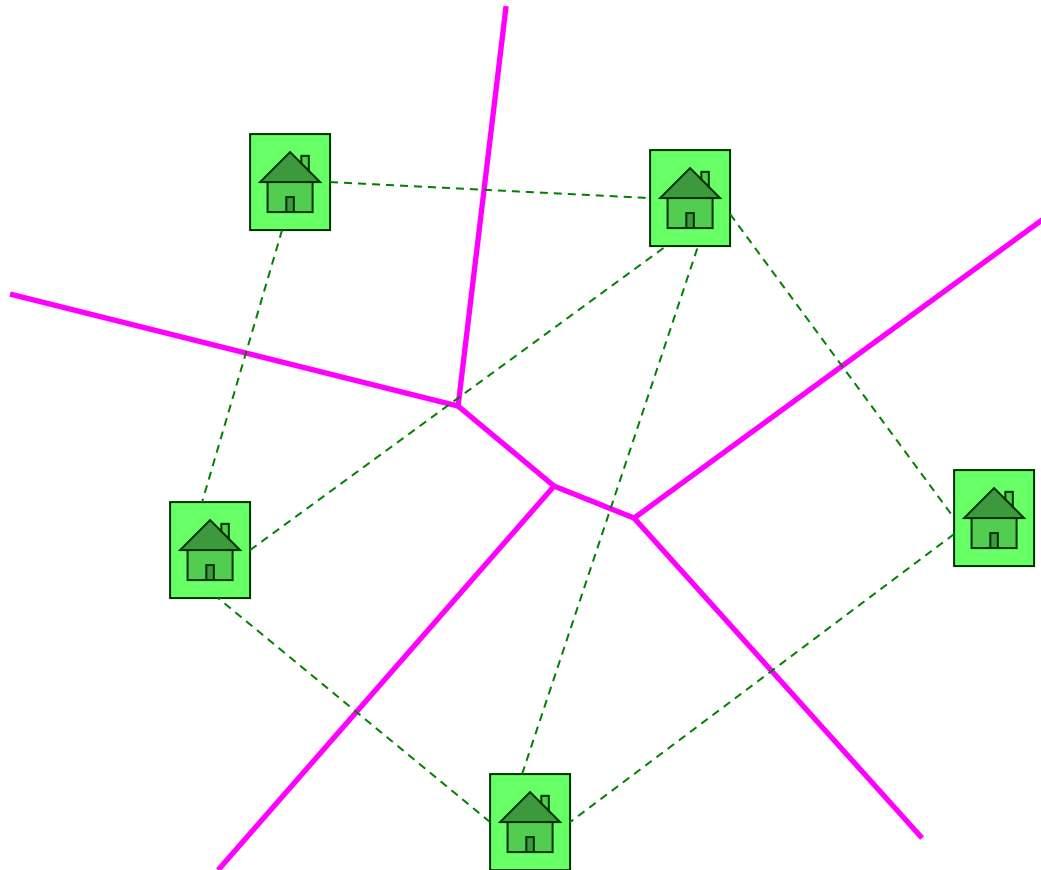
Closest café on campus?



Voronoi diagram

Example 1 – Proximity

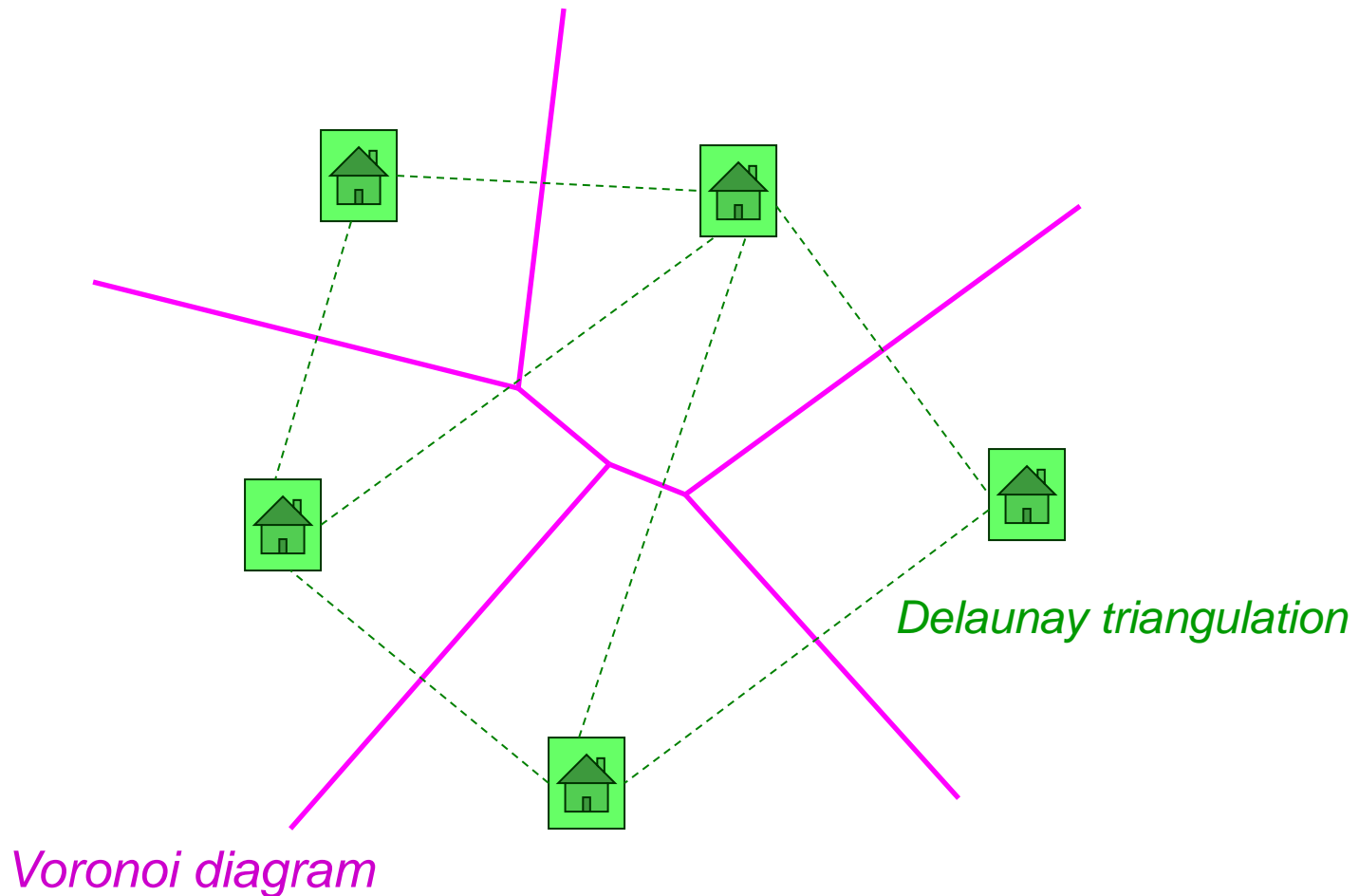
Closest café on campus?



Voronoi diagram

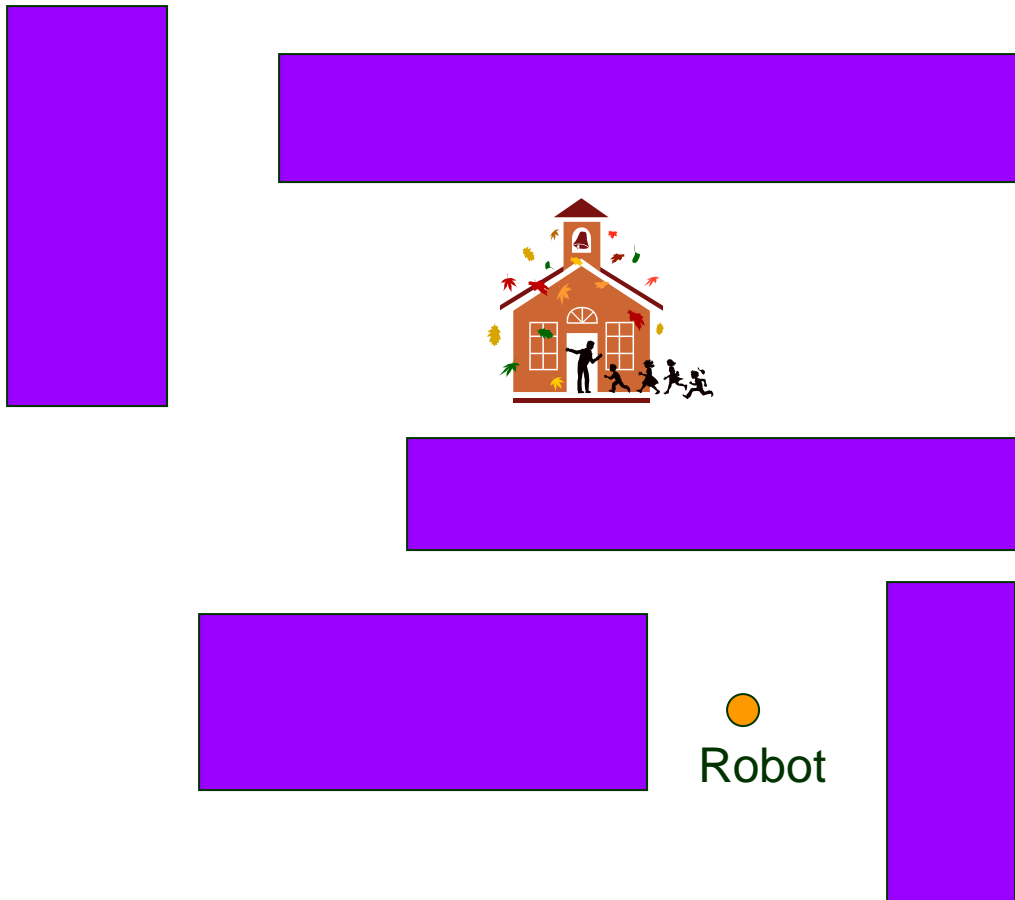
Example 1 – Proximity

Closest café on campus?



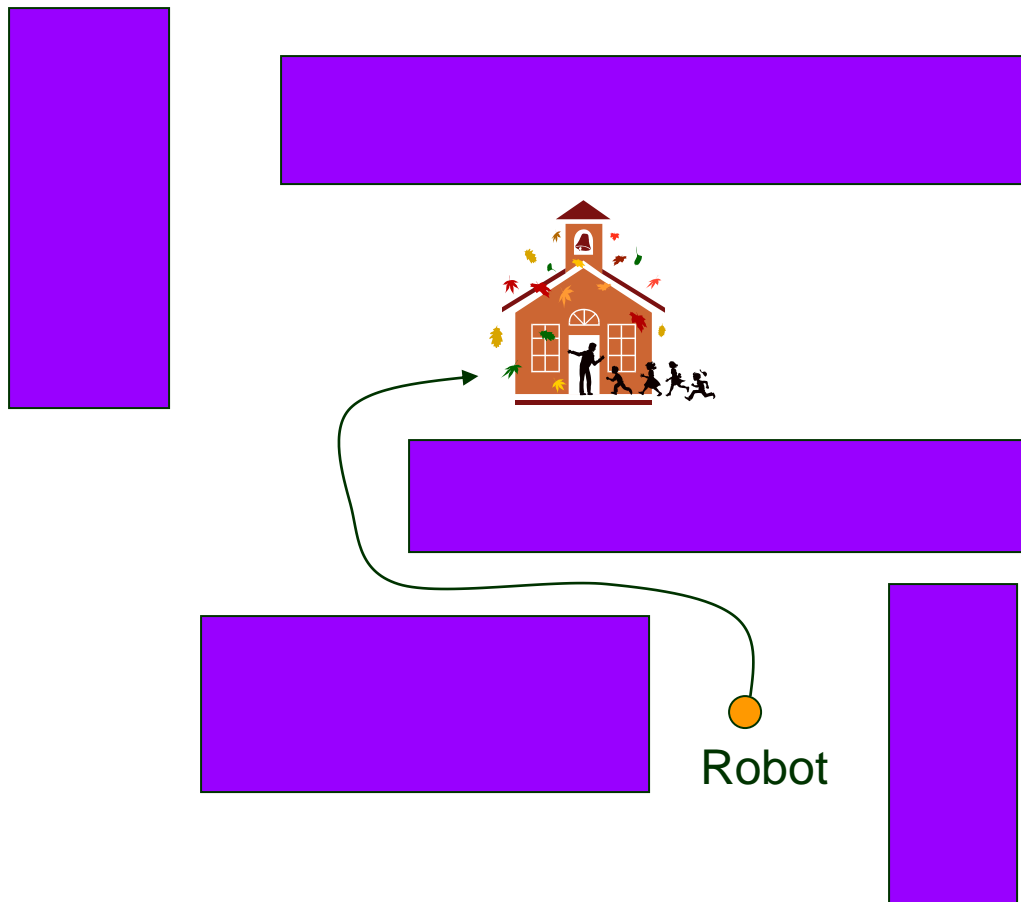
Example 2 – Path Planning

How can a robot find a *short* route to the destination that avoids all obstacles?



Example 2 – Path Planning

How can a robot find a *short* route to the destination that avoids all obstacles?



Applications in Computer Graphics

Creating scene images on a display device.

- Intersect geometric primitives (lines, polygons, polyhedra, etc.).
- Determine primitives lying in a region.
- *Hidden surface removal* – determine the visible part of a 3D scene while discard the occluded part from a viewpoint.
- Create realistic-looking scenes – taking into account lighting and computing shadows.
- Deal with moving objects and detect collisions.

Applications in Robotics

How the robot perceives, understands, and acts upon its environment:

- Motion/path planning
- Grasping
- Parts orienting
- Optimal placement

Applications in GIS

Storage of geographical data (contours of countries, height of mountains, course of rivers, population, roads, electricity lines, etc.)

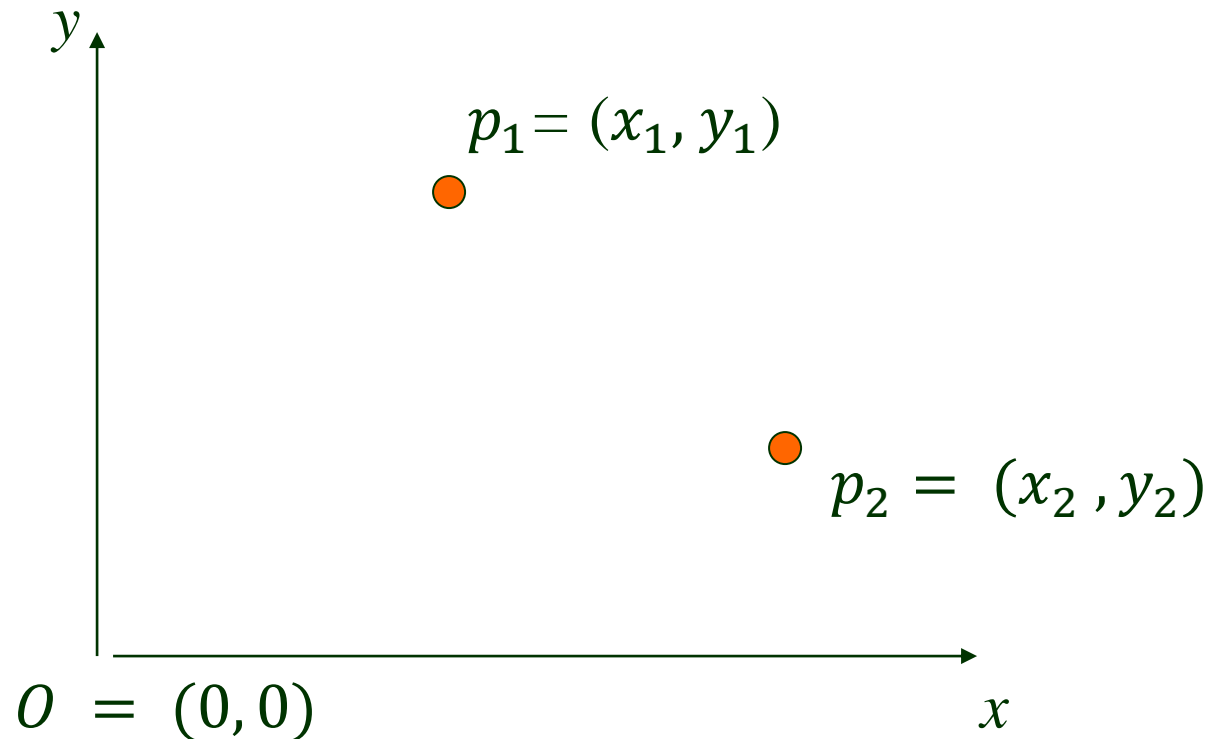
- Large amount of data – requiring efficient algorithms
- Geographic data storage (e.g., map of roads for car positioning or computer display)
- Interpolation between nearby sample data points
- Overlay of multiple maps

Applications in CAD/CAM

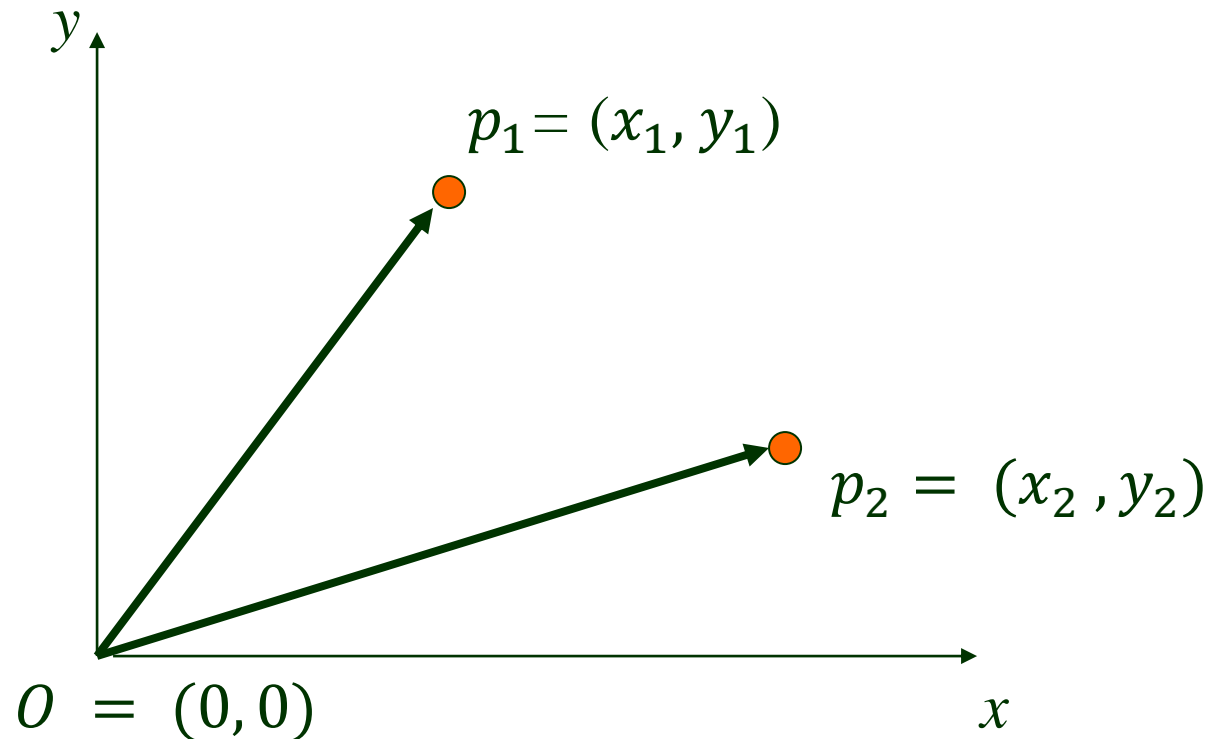
Design of products with a computer

- Intersection, union, and decomposition of objects
- Testing on product specifications
- Testing design for feasibility
- *Design for assembly* – modeling and simulation of assembly

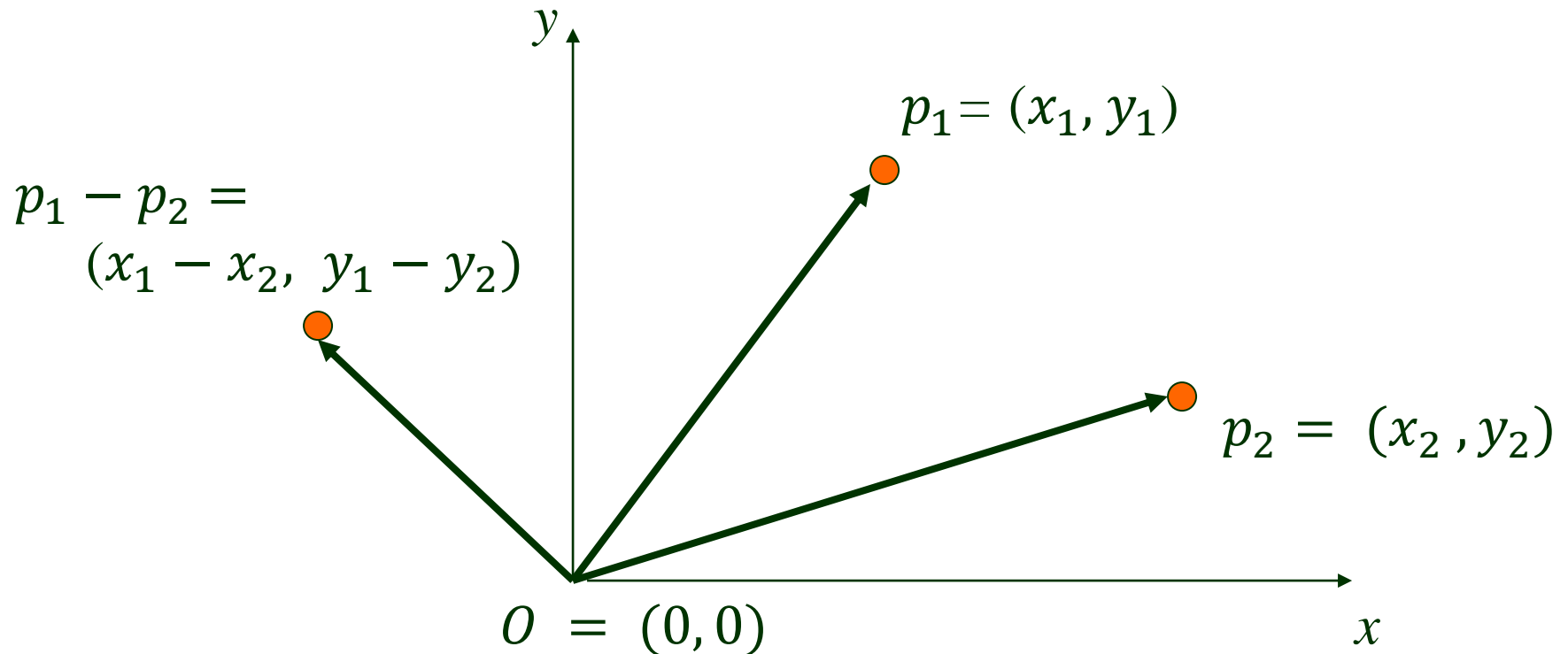
Line Segments & Vectors



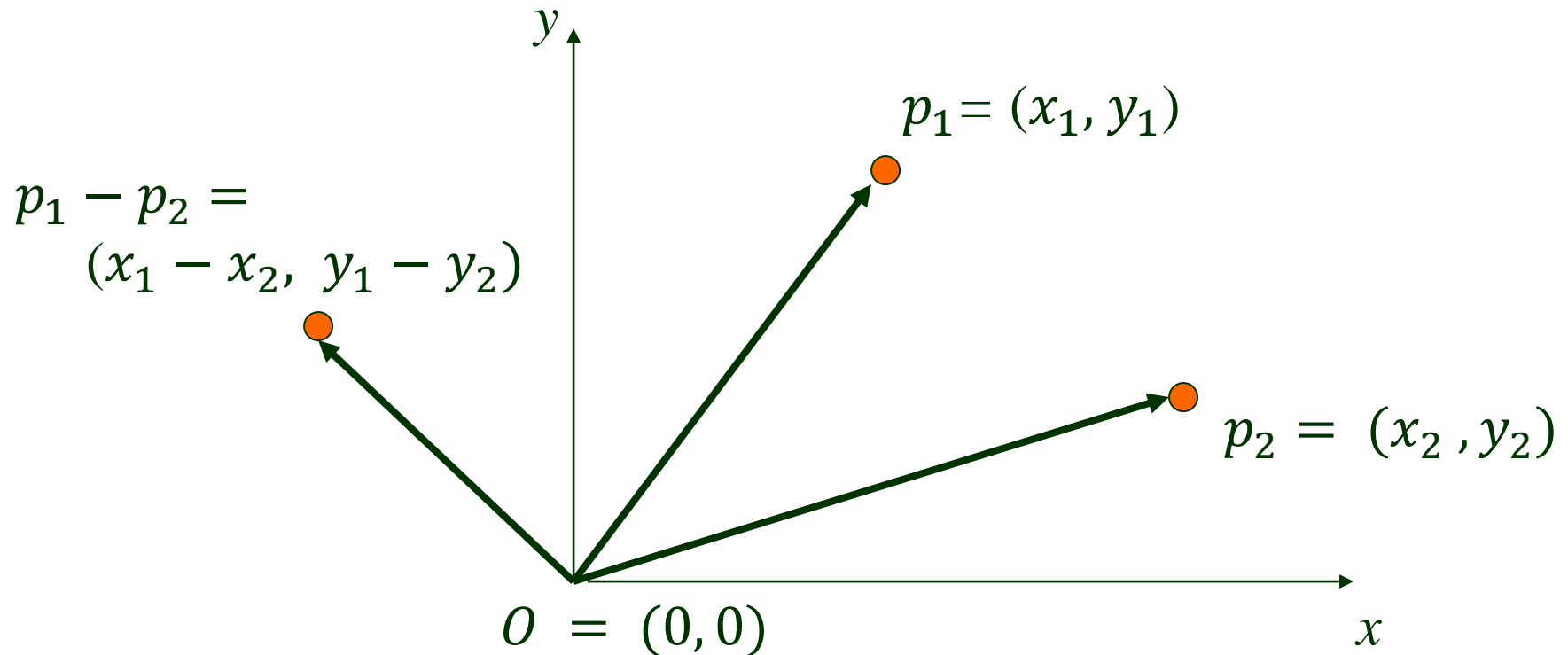
Line Segments & Vectors



Line Segments & Vectors

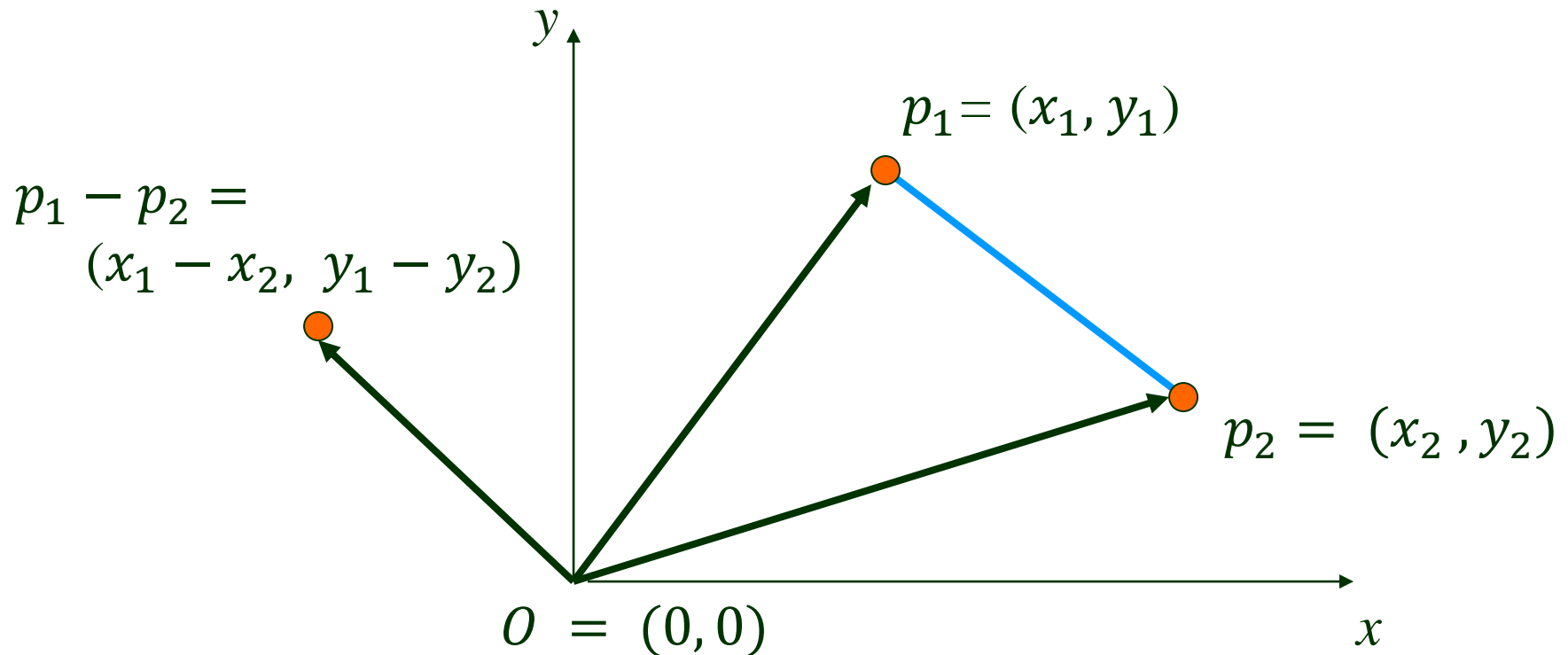


Line Segments & Vectors



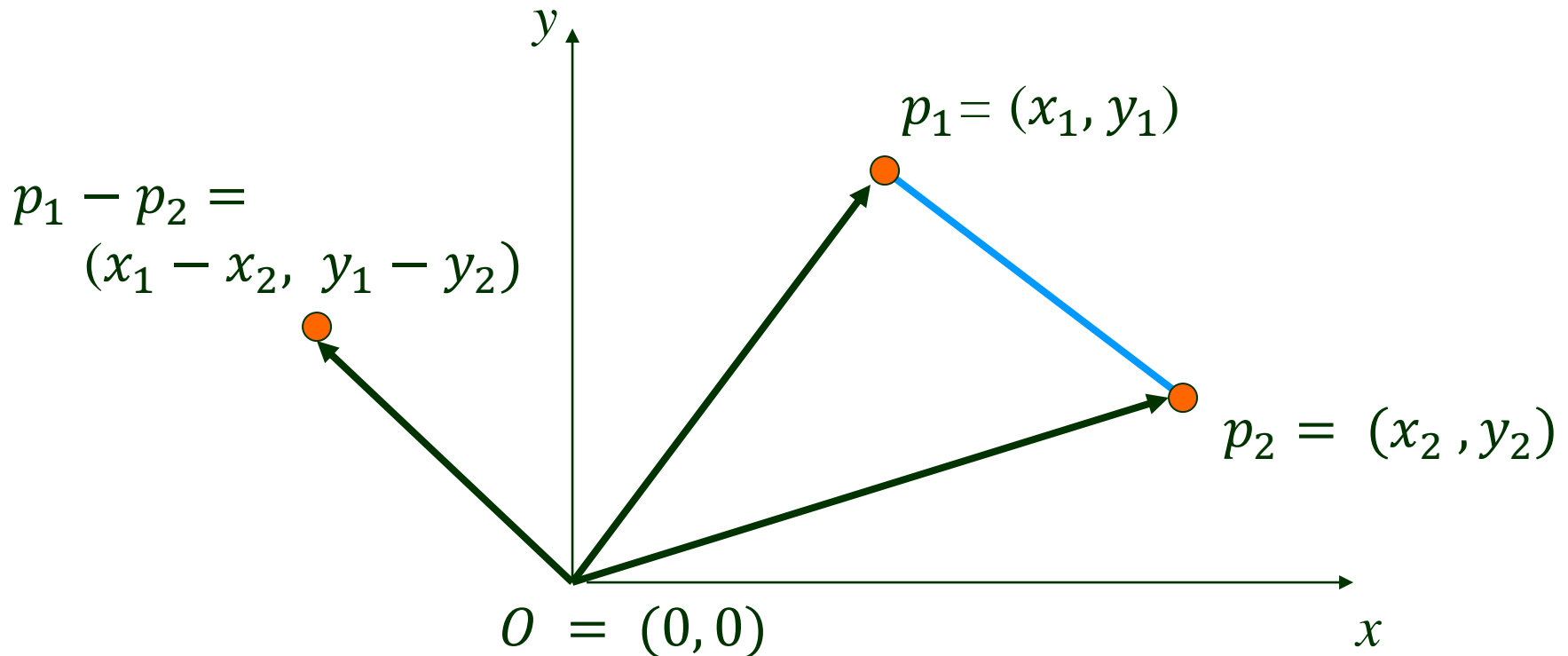
Points (vectors): $p_1, p_2, p_1 - p_2 = \overrightarrow{p_2 p_1}$

Line Segments & Vectors



Points (vectors): $p_1, p_2, p_1 - p_2 = \overrightarrow{p_2 p_1}$

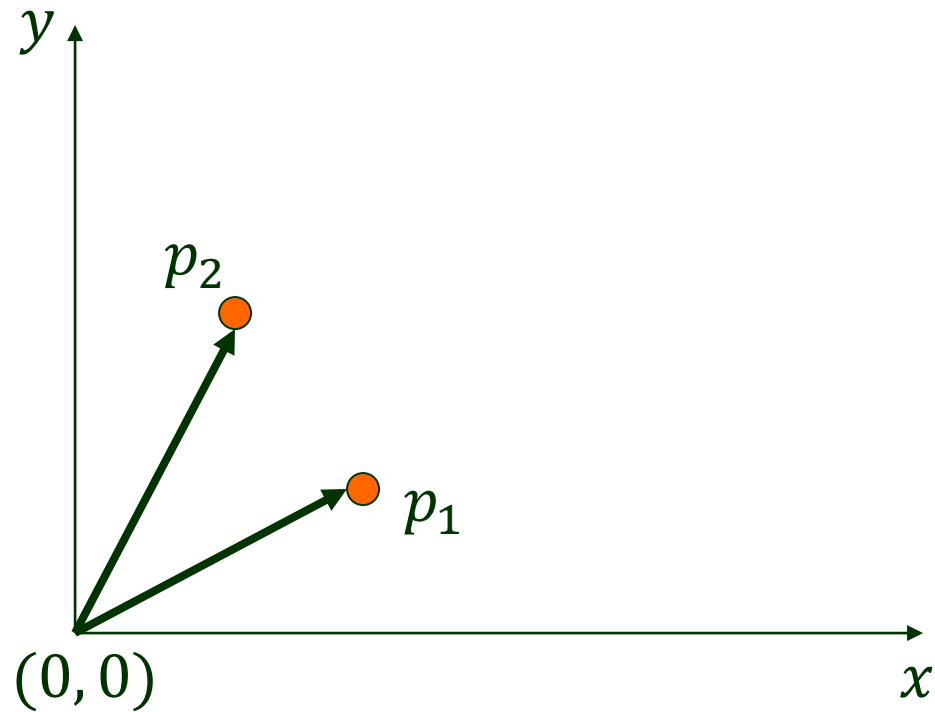
Line Segments & Vectors



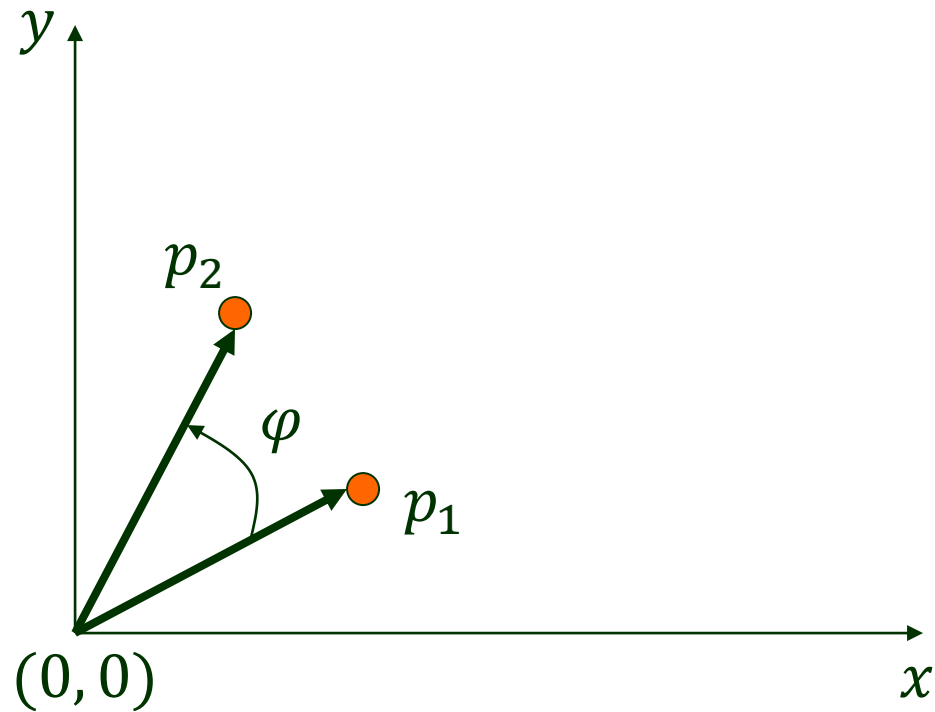
Points (vectors): $p_1, p_2, p_1 - p_2 = \overrightarrow{p_2 p_1}$

Line segment: $\overline{p_2 p_1} = \overline{p_1 p_2}$

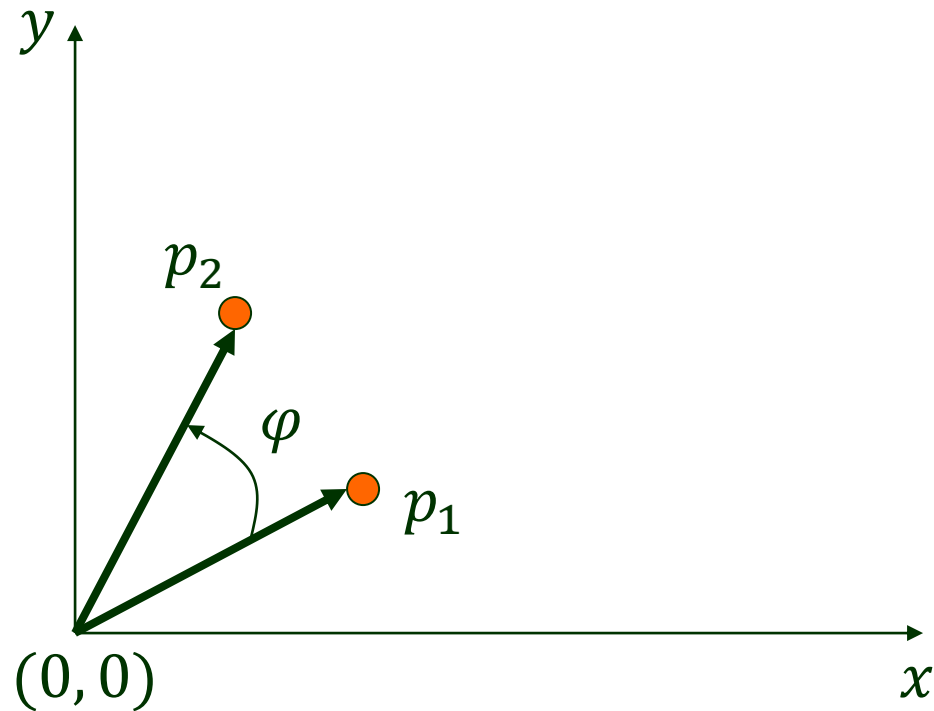
Dot (Inner) Product



Dot (Inner) Product

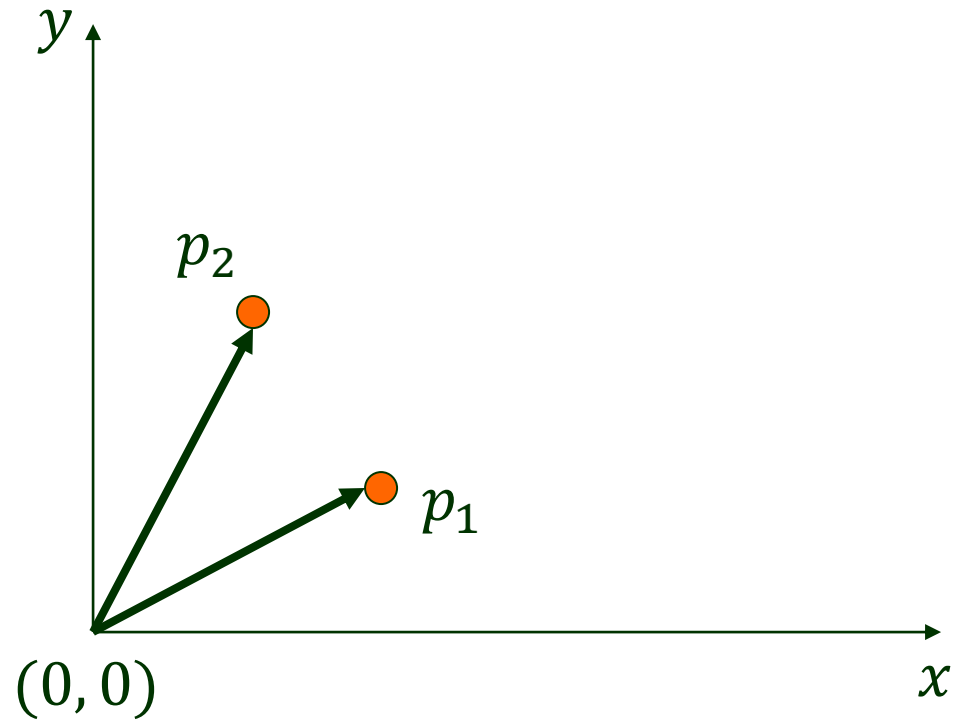


Dot (Inner) Product

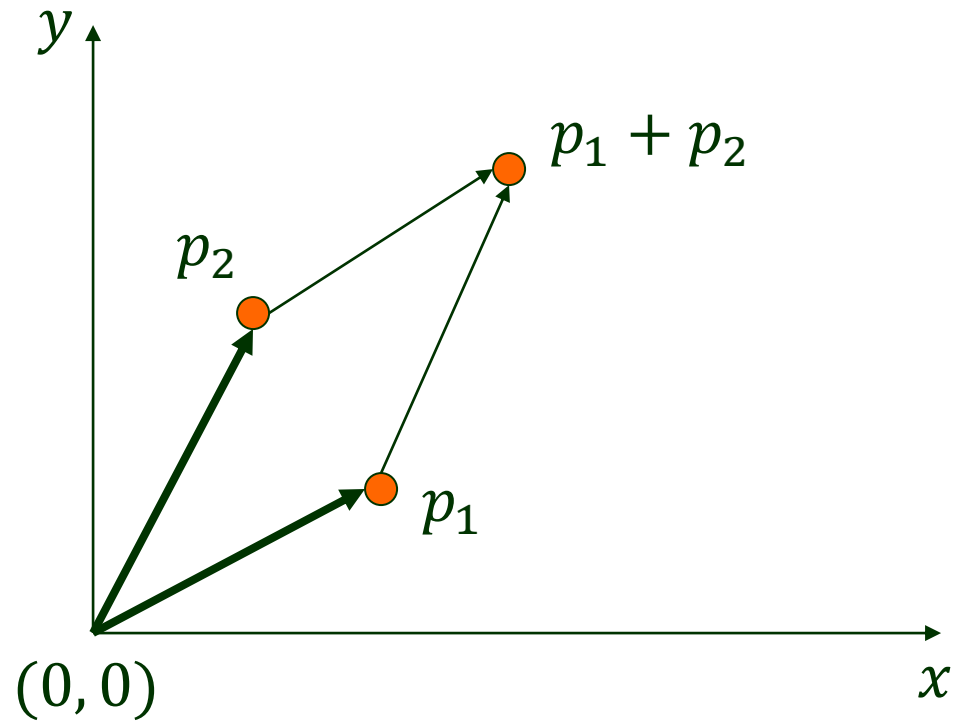


$$p_1 \cdot p_2 = x_1 x_2 + y_1 y_2 = p_2 \cdot p_1 = |p_1| |p_2| \cos \varphi$$

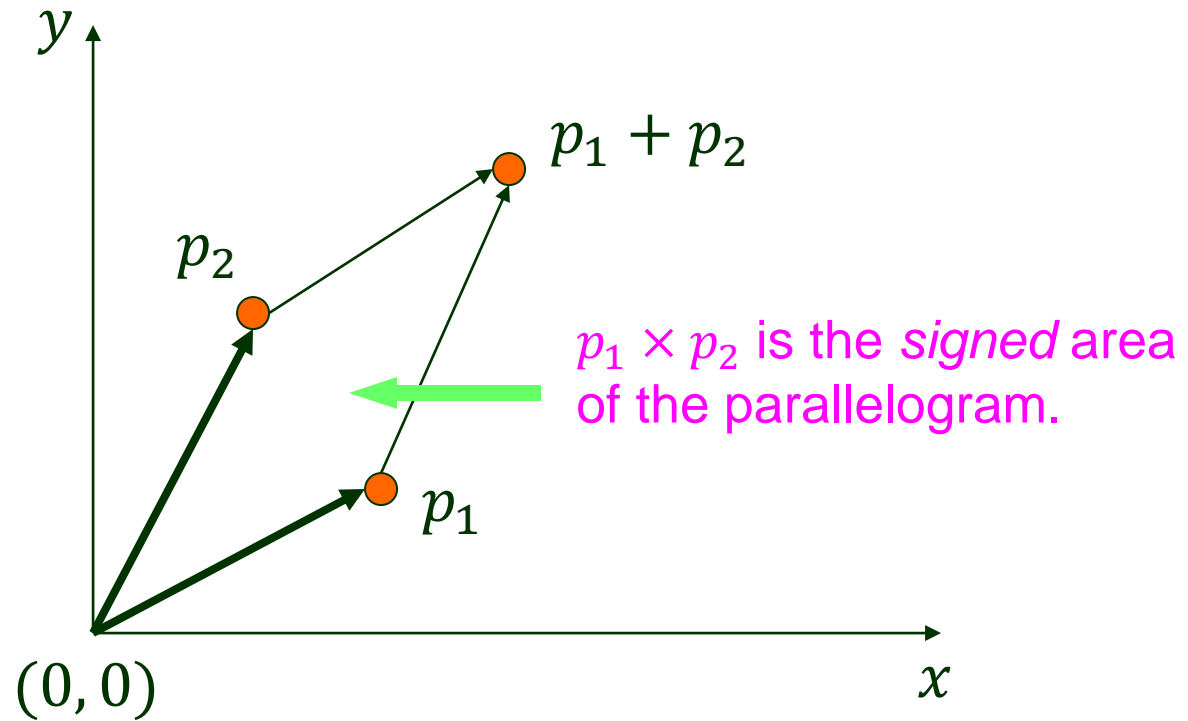
Cross (Vector) Product



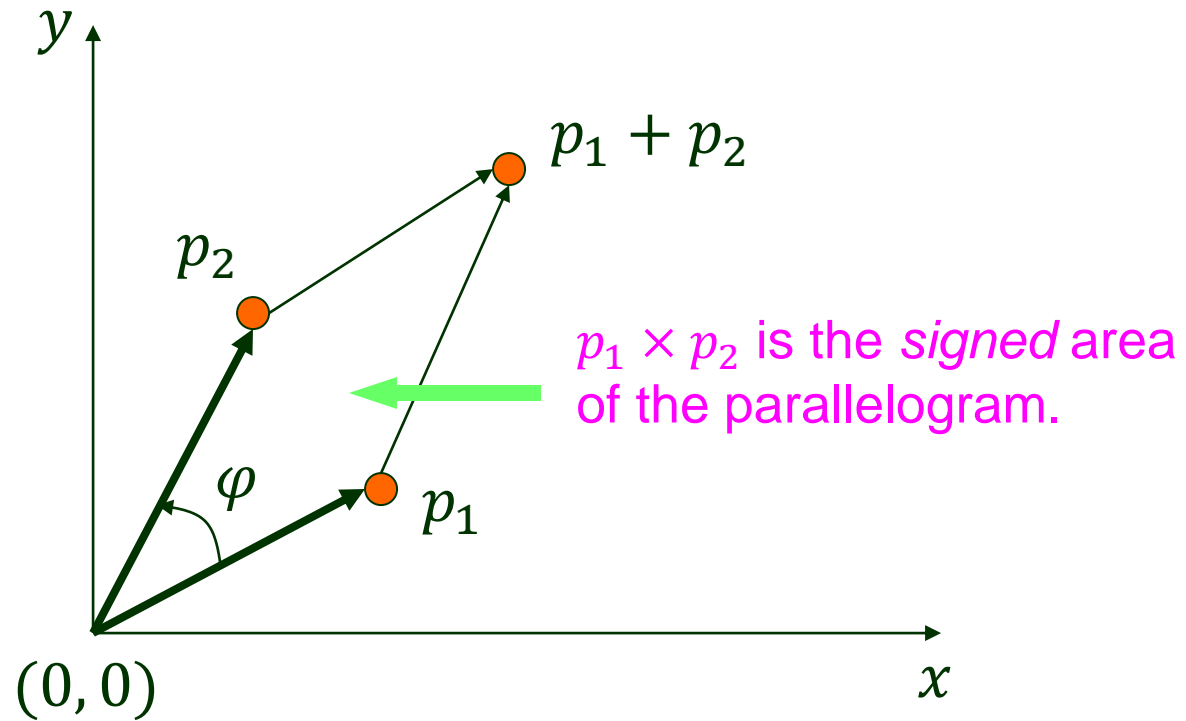
Cross (Vector) Product



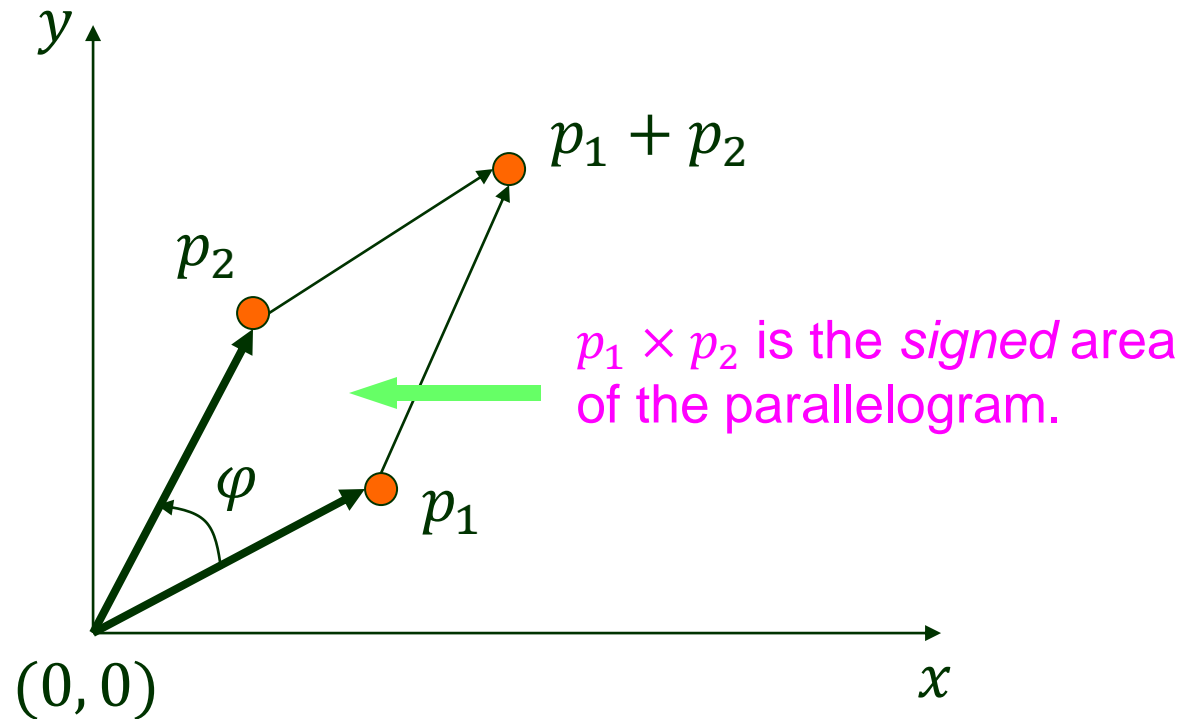
Cross (Vector) Product



Cross (Vector) Product

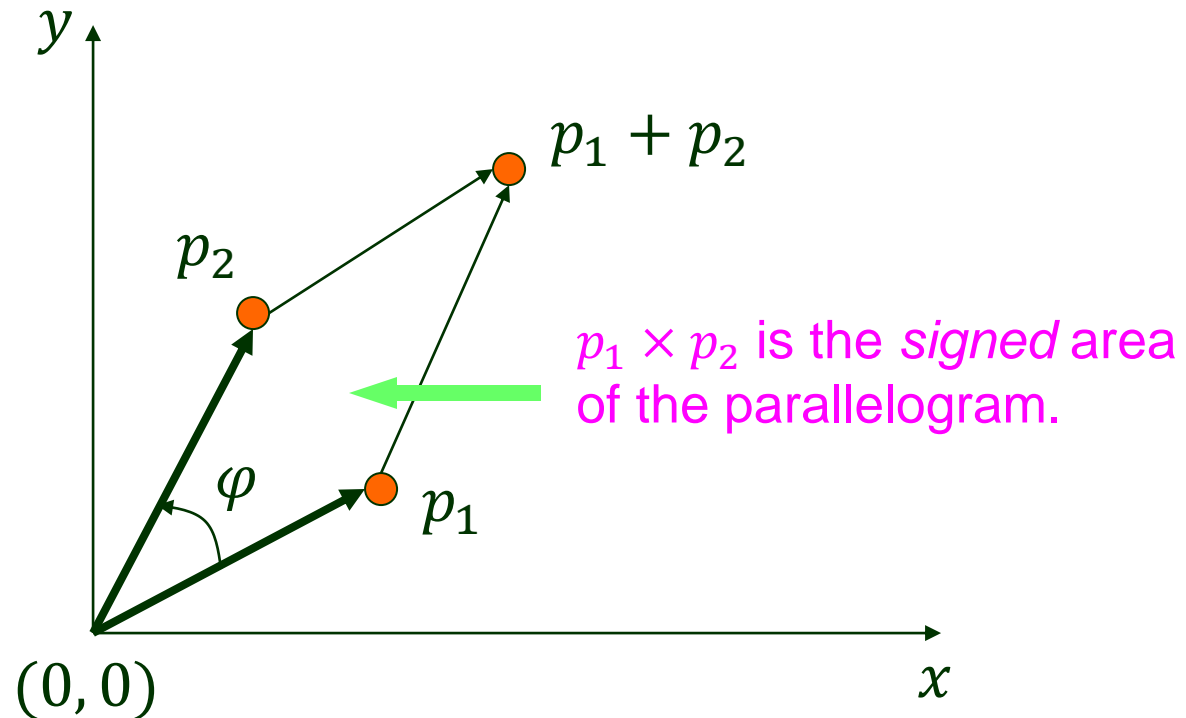


Cross (Vector) Product



$$p_1 \times p_2 = x_1 y_2 - x_2 y_1 = -p_2 \times p_1 = |p_1| |p_2| \sin \varphi$$

Cross (Vector) Product



$$p_1 \times p_2 = x_1 y_2 - x_2 y_1 = -p_2 \times p_1 = |p_1| |p_2| \sin \varphi$$

p_1 and p_2 are *collinear* with the origin iff $p_1 \times p_2 = 0$.

Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .

Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .

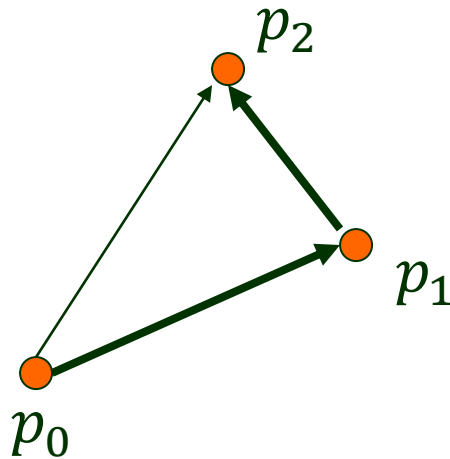
Counterclockwise

Clockwise

Turn of 0 or π

Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .



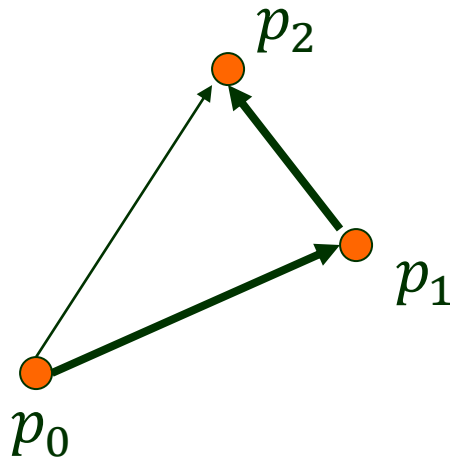
Counterclockwise

Clockwise

Turn of 0 or π

Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .



Counterclockwise

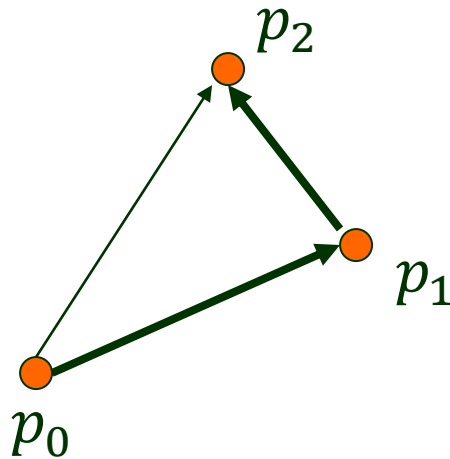
Clockwise

Turn of 0 or π

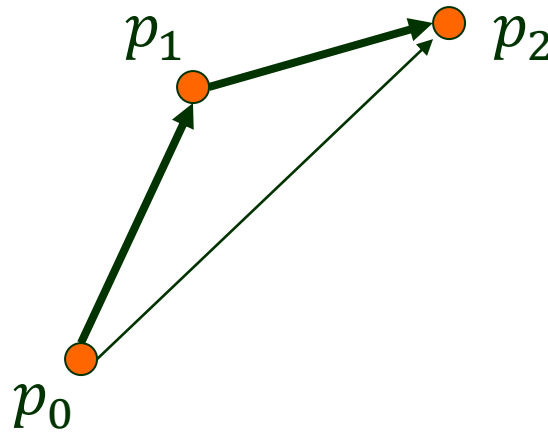
$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} > 0$$

Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .



Counterclockwise



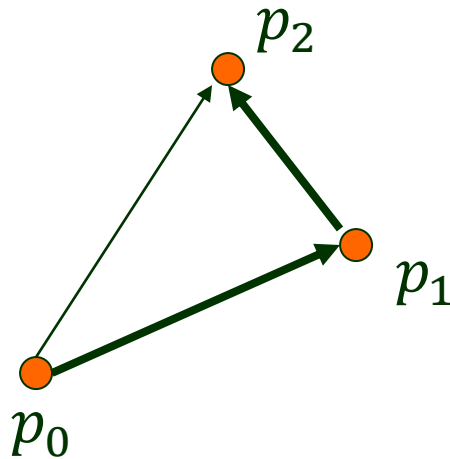
Clockwise

Turn of 0 or π

$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} > 0$$

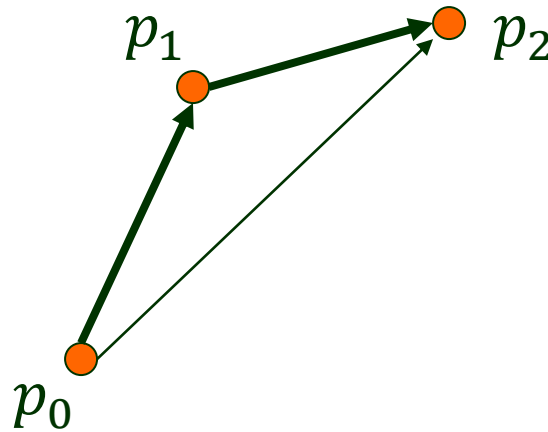
Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .



Counterclockwise

$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} > 0$$



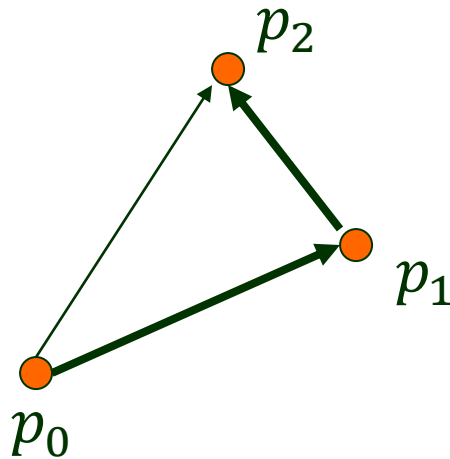
Clockwise

$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} < 0$$

Turn of 0 or π

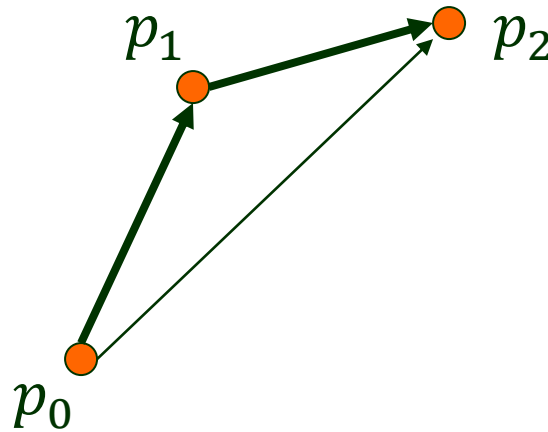
Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .



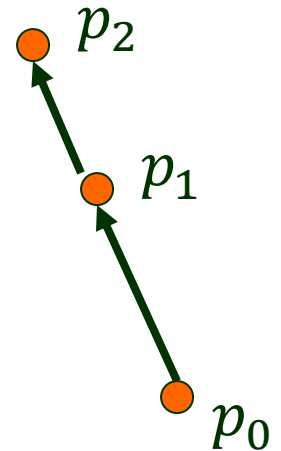
Counterclockwise

$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} > 0$$



Clockwise

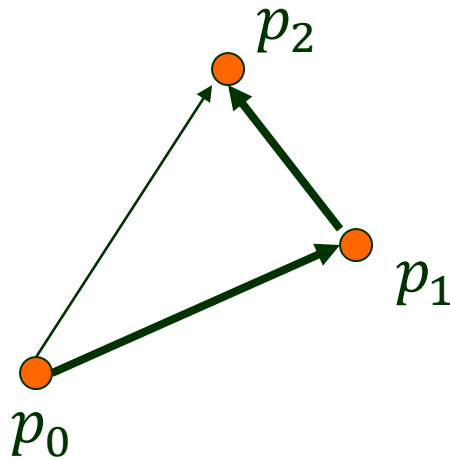
$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} < 0$$



Turn of 0 or π

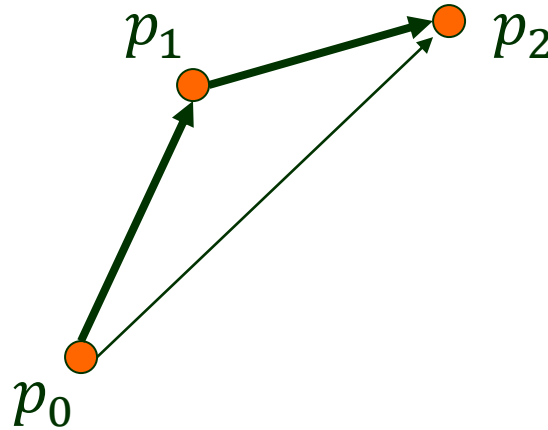
Turning of Consecutive Segments

Segments $\overline{p_0p_1}$ and $\overline{p_1p_2}$. Move from p_0 to p_1 then to p_2 .



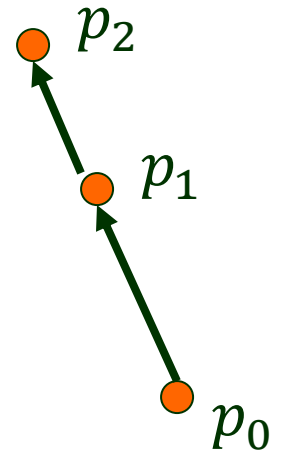
Counterclockwise

$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} > 0$$



Clockwise

$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} < 0$$



Turn of 0 or π

$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} = 0$$

Case of Collinearity

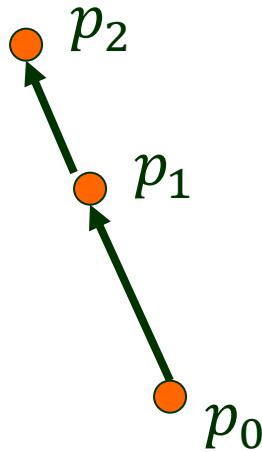
$$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} = 0 \implies p_1, p_2, p_3 \text{ are collinear.}$$

No change of direction

Direction reversal

Case of Collinearity

$$\overrightarrow{p_0 p_1} \times \overrightarrow{p_1 p_2} = 0 \implies p_0, p_1, p_2 \text{ are collinear.}$$

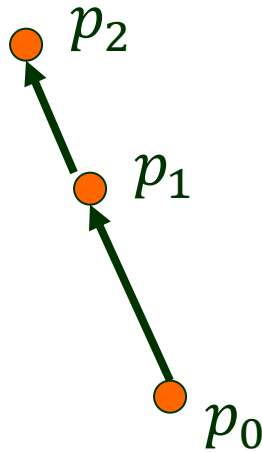


No change of direction

Direction reversal

Case of Collinearity

$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} = 0 \implies p_1, p_2, p_3$ are collinear.



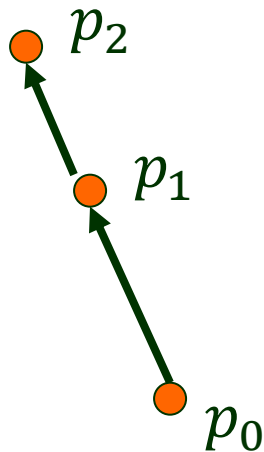
No change of direction

Direction reversal

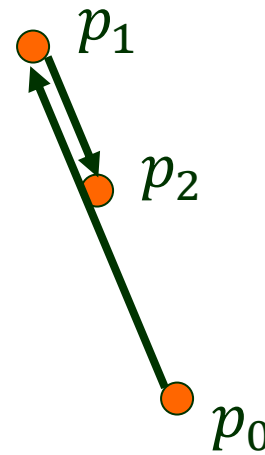
$$\overrightarrow{p_0p_1} \cdot \overrightarrow{p_1p_2} > 0$$

Case of Collinearity

$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} = 0 \implies p_1, p_2, p_3$ are collinear.



No change of direction

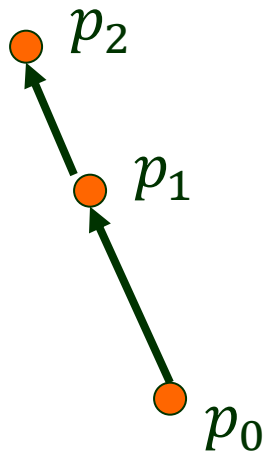


Direction reversal

$$\overrightarrow{p_0p_1} \cdot \overrightarrow{p_1p_2} > 0$$

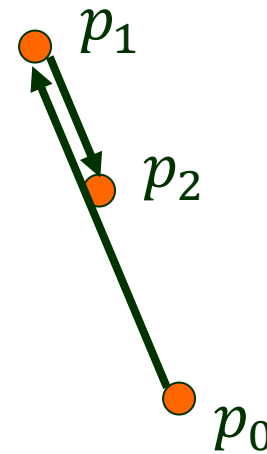
Case of Collinearity

$\overrightarrow{p_0p_1} \times \overrightarrow{p_1p_2} = 0 \implies p_1, p_2, p_3$ are collinear.



No change of direction

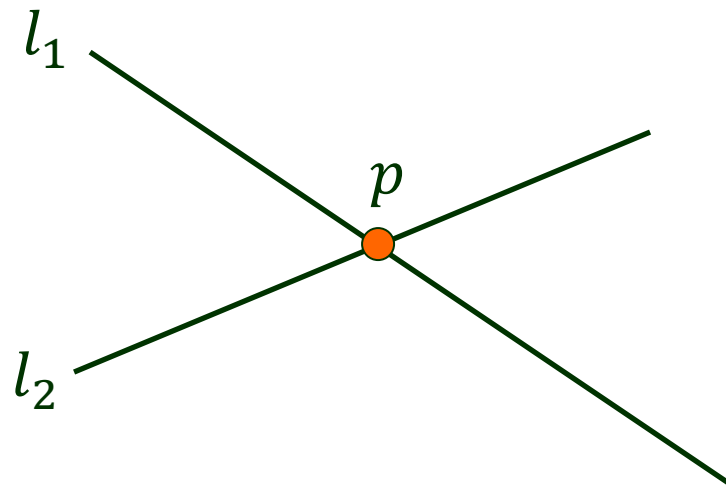
$$\overrightarrow{p_0p_1} \cdot \overrightarrow{p_1p_2} > 0$$



Direction reversal

$$\overrightarrow{p_0p_1} \cdot \overrightarrow{p_1p_2} < 0$$

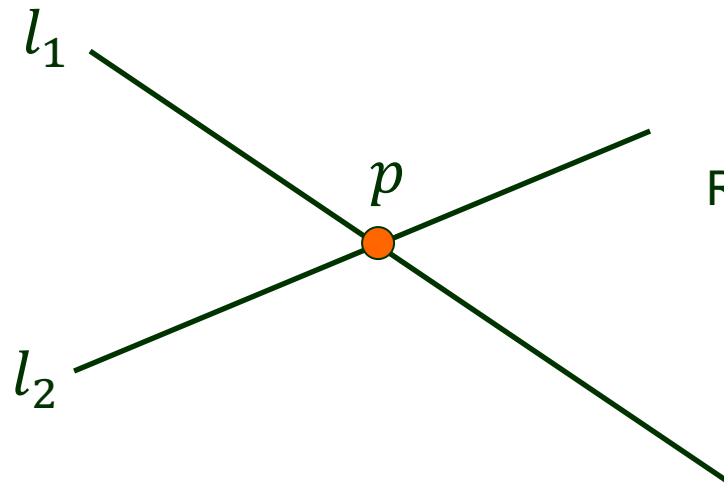
Intersection of Two Lines*



$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

Intersection of Two Lines*



$$l_1: a_1x + b_1y + c_1 = 0$$

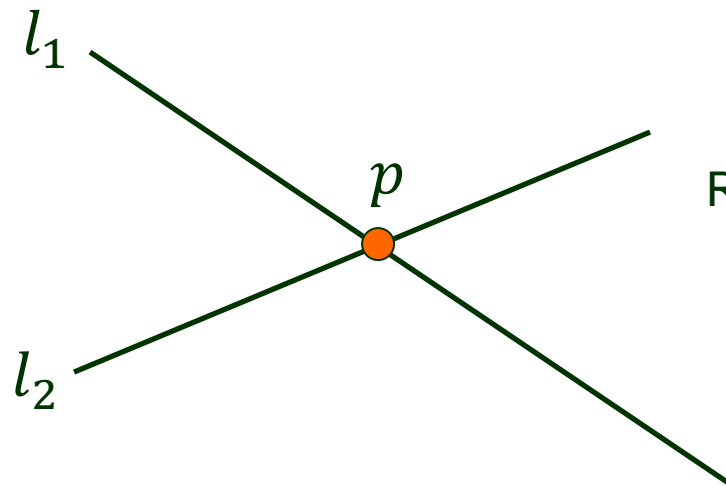
$$l_2: a_2x + b_2y + c_2 = 0$$

Rewrite the above equations as dot products:

$$(a_1, b_1, c_1) \cdot (x, y, 1) = 0$$

$$(a_2, b_2, c_2) \cdot (x, y, 1) = 0$$

Intersection of Two Lines*



$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

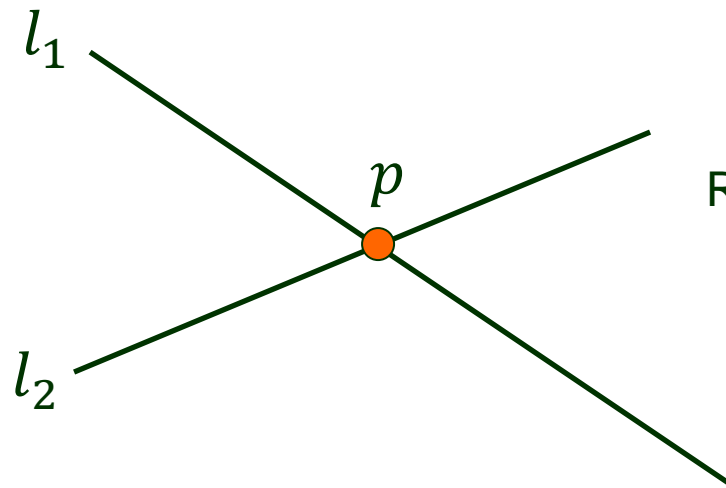
Rewrite the above equations as dot products:

$$(a_1, b_1, c_1) \cdot (x, y, 1) = 0$$

$$(a_2, b_2, c_2) \cdot (x, y, 1) = 0$$

Hence $(x, y, 1)$ is perpendicular to both (a_1, b_1, c_1) and (a_2, b_2, c_2) .

Intersection of Two Lines*



$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

Rewrite the above equations as dot products:

$$(a_1, b_1, c_1) \cdot (x, y, 1) = 0$$

$$(a_2, b_2, c_2) \cdot (x, y, 1) = 0$$

Hence $(x, y, 1)$ is perpendicular to both (a_1, b_1, c_1) and (a_2, b_2, c_2) .

$(x, y, 1)$ must be **parallel to their cross product!**

Homogeneous Coordinates*

Represent every point (x, y) as $(x, y, 1)$.

homogeneous coordinates of (x, y)

Homogeneous Coordinates*

Represent every point (x, y) as $(x, y, 1)$.

homogeneous coordinates of (x, y)

Intersection $(x, y, 1)$ is parallel to the cross product vector:

$$(a_1, b_1, c_1) \times (a_2, b_2, c_2) = (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1)$$

Homogeneous Coordinates*

Represent every point (x, y) as $(x, y, 1)$.

homogeneous coordinates of (x, y)

Intersection $(x, y, 1)$ is parallel to the cross product vector:

$$(a_1, b_1, c_1) \times (a_2, b_2, c_2) = (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1)$$

homogeneous coordinates of intersection

Homogeneous Coordinates*

Represent every point (x, y) as $(x, y, 1)$.

homogeneous coordinates of (x, y)

Intersection $(x, y, 1)$ is parallel to the cross product vector:

$$(a_1, b_1, c_1) \times (a_2, b_2, c_2) = (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1)$$

homogeneous coordinates of intersection

Normalize the z-coordinate of the cross product to 1.

$$\left(\frac{b_1c_2 - b_2c_1}{a_1b_2 - a_2b_1}, \frac{c_1a_2 - c_2a_1}{a_1b_2 - a_2b_1}, 1 \right)$$

Homogeneous Coordinates*

Represent every point (x, y) as $(x, y, 1)$.

homogeneous coordinates of (x, y)

Intersection $(x, y, 1)$ is parallel to the cross product vector:

$$(a_1, b_1, c_1) \times (a_2, b_2, c_2) = (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1)$$

homogeneous coordinates of intersection

Normalize the z-coordinate of the cross product to 1.

$$\left(\frac{b_1c_2 - b_2c_1}{a_1b_2 - a_2b_1}, \frac{c_1a_2 - c_2a_1}{a_1b_2 - a_2b_1}, 1 \right)$$

Homogeneous Coordinates*

Represent every point (x, y) as $(x, y, 1)$.

homogeneous coordinates of (x, y)

Intersection $(x, y, 1)$ is parallel to the cross product vector:

$$(a_1, b_1, c_1) \times (a_2, b_2, c_2) = (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1)$$

homogeneous coordinates of intersection

Normalize the z-coordinate of the cross product to 1.

$$\left(\frac{b_1c_2 - b_2c_1}{a_1b_2 - a_2b_1}, \frac{c_1a_2 - c_2a_1}{a_1b_2 - a_2b_1}, 1 \right)$$

Hence the intersection point:

$$\left(\frac{b_1c_2 - b_2c_1}{a_1b_2 - a_2b_1}, \frac{c_1a_2 - c_2a_1}{a_1b_2 - a_2b_1} \right)$$

Intersection Example*

Find the intersect point of the lines:

$$x - 7y + 8 = 0$$

$$3x - 4y + 1 = 0$$

Intersection Example*

Find the intersect point of the lines:

$$x - 7y + 8 = 0 \quad 3x - 4y + 1 = 0$$

Take the cross product of the two coefficient vectors:

$$(1, -7, 8) \times (3, -4, 1) = (25, 23, 17)$$

Intersection Example*

Find the intersect point of the lines:

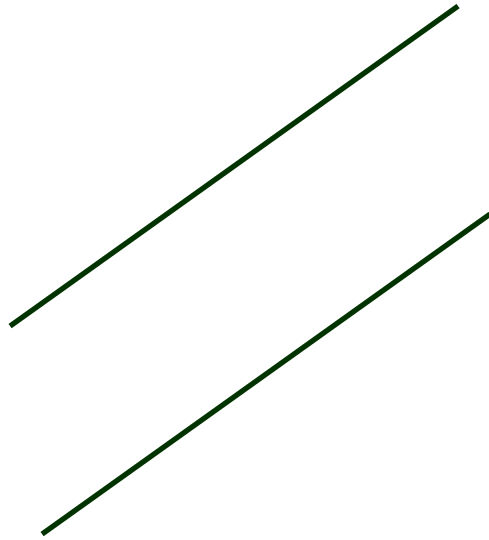
$$x - 7y + 8 = 0 \qquad 3x - 4y + 1 = 0$$

Take the cross product of the two coefficient vectors:

$$(1, -7, 8) \times (3, -4, 1) = (25, 23, 17)$$

Intersection point: $\left(\frac{25}{17}, \frac{23}{17}\right)$

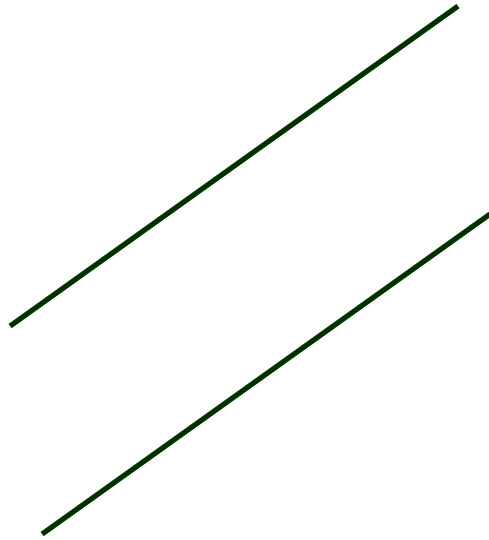
Two Parallel Lines*



$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

Two Parallel Lines*

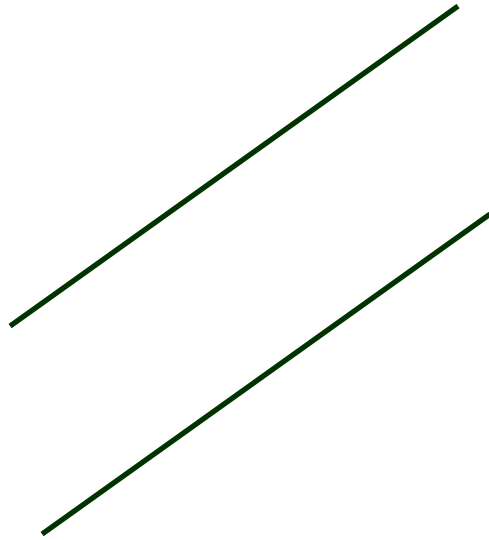


$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

$$a_1b_2 - b_1a_2 = 0$$

Two Parallel Lines*



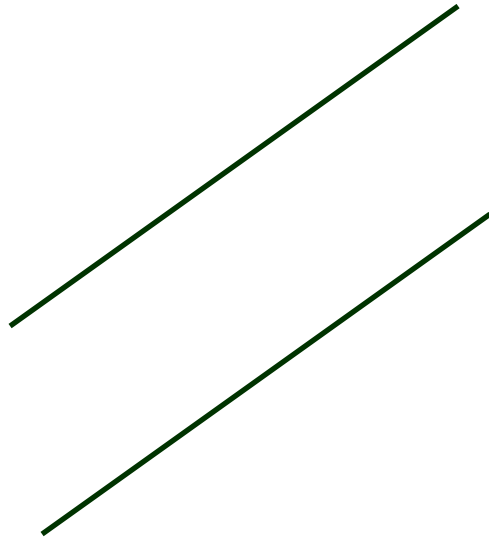
$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

$$a_1b_2 - b_1a_2 = 0$$

$$(a_1, b_1, c_1) \times (a_2, b_2, c_2) = (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1)$$

Two Parallel Lines*



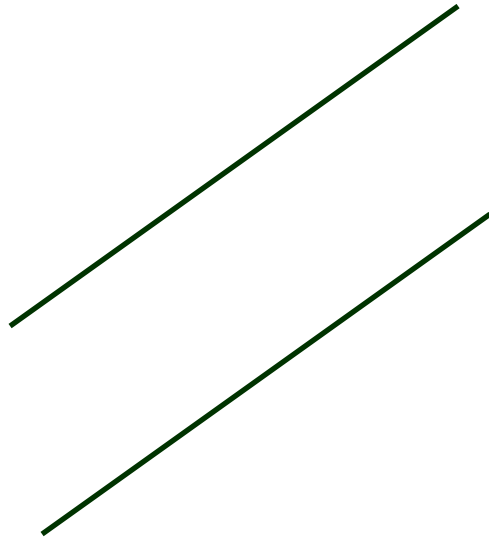
$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

$$a_1b_2 - b_1a_2 = 0$$

$$\begin{aligned}(a_1, b_1, c_1) \times (a_2, b_2, c_2) &= (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1) \\ &= (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, \mathbf{0})\end{aligned}$$

Two Parallel Lines*



$$l_1: a_1x + b_1y + c_1 = 0$$

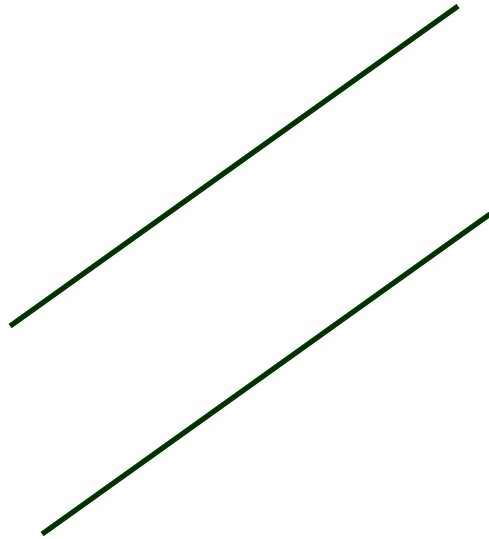
$$l_2: a_2x + b_2y + c_2 = 0$$

$$a_1b_2 - b_1a_2 = 0$$

$$\begin{aligned}(a_1, b_1, c_1) \times (a_2, b_2, c_2) &= (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1) \\ &= (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, \mathbf{0})\end{aligned}$$

↑
point at infinity

Two Parallel Lines*



$$l_1: a_1x + b_1y + c_1 = 0$$

$$l_2: a_2x + b_2y + c_2 = 0$$

$$a_1b_2 - b_1a_2 = 0$$

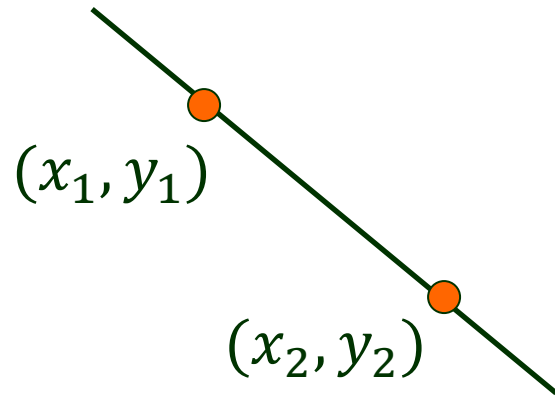
$$\begin{aligned}(a_1, b_1, c_1) \times (a_2, b_2, c_2) &= (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, a_1b_2 - a_2b_1) \\ &= (b_1c_2 - b_2c_1, c_1a_2 - c_2a_1, \mathbf{0})\end{aligned}$$

↑
point at infinity

Two parallel lines “intersect” at infinity.

Line through Two Points*

$$ax + by + c = 0?$$



Line through Two Points*

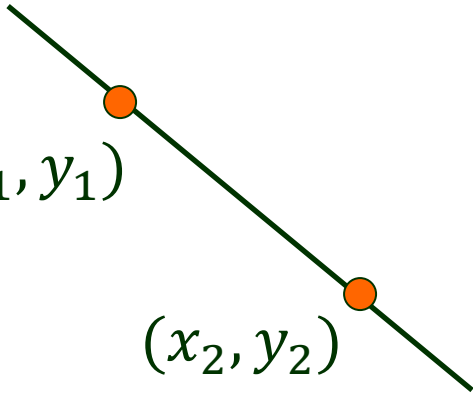
$$ax + by + c = 0?$$

(x_1, y_1)

(x_2, y_2)

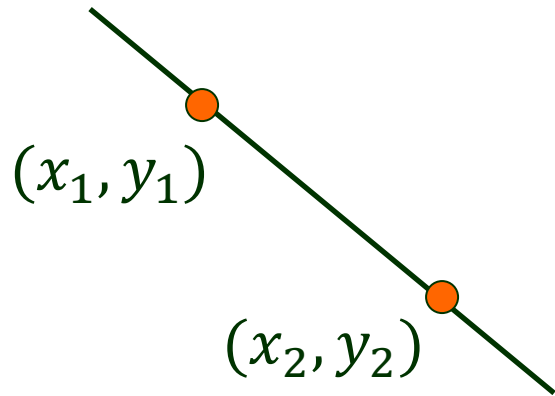
$$ax_1 + by_1 + c = 0$$

$$ax_2 + by_2 + c = 0$$



Line through Two Points*

$$ax + by + c = 0?$$



$$ax_1 + by_1 + c = 0$$

$$ax_2 + by_2 + c = 0$$

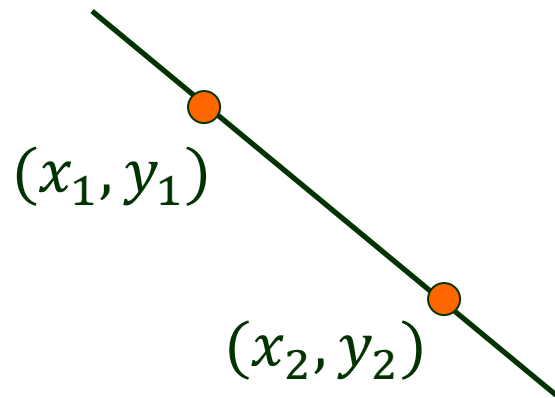


$$(a, b, c) \cdot (x_1, y_1, 1) = 0$$

$$(a, b, c) \cdot (x_2, y_2, 1) = 0$$

Line through Two Points*

$$ax + by + c = 0?$$



$$ax_1 + by_1 + c = 0$$

$$ax_2 + by_2 + c = 0$$



$$(a, b, c) \cdot (x_1, y_1, 1) = 0$$

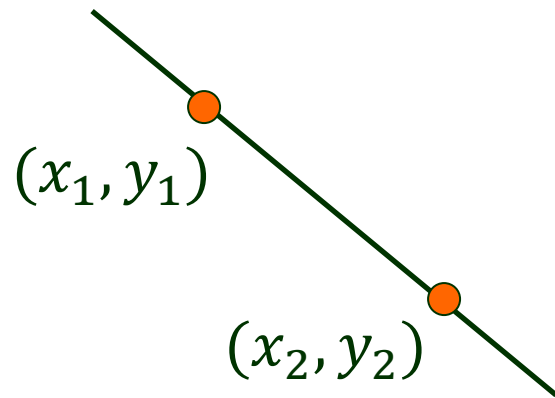
$$(a, b, c) \cdot (x_2, y_2, 1) = 0$$



$$(a, b, c) = (x_1, y_1, 1) \times (x_2, y_2, 1)$$

Line through Two Points*

$$ax + by + c = 0?$$



$$ax_1 + by_1 + c = 0$$

$$ax_2 + by_2 + c = 0$$



$$(a, b, c) \cdot (x_1, y_1, 1) = 0$$

$$(a, b, c) \cdot (x_2, y_2, 1) = 0$$

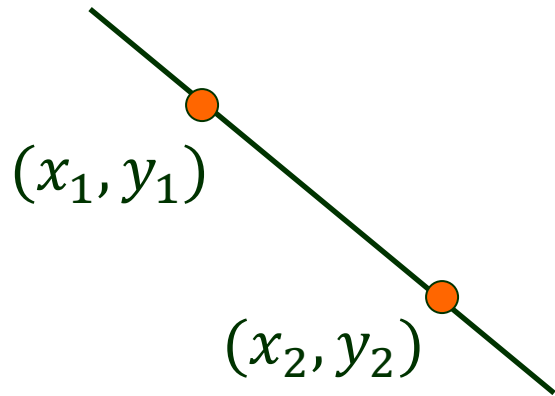


$$(a, b, c) = (x_1, y_1, 1) \times (x_2, y_2, 1)$$

Scaling yields the same line!

Line through Two Points*

$$ax + by + c = 0?$$



$$ax_1 + by_1 + c = 0$$

$$ax_2 + by_2 + c = 0$$



$$(a, b, c) \cdot (x_1, y_1, 1) = 0$$

$$(a, b, c) \cdot (x_2, y_2, 1) = 0$$



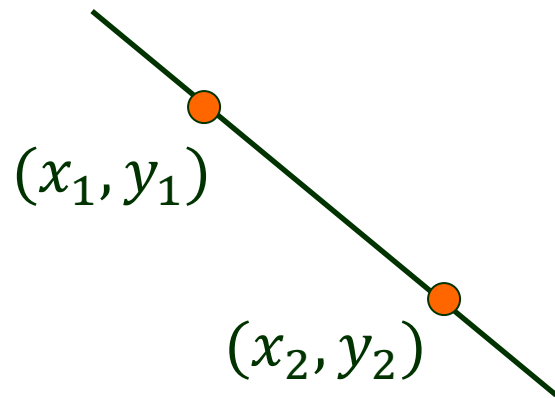
$$(a, b, c) = (x_1, y_1, 1) \times (x_2, y_2, 1)$$

Scaling yields the same line!

Ex. The line through $(3, 1)$ and $(-4, 5)$ has coefficients (i.e., homogeneous coordinates)

Line through Two Points*

$$ax + by + c = 0?$$



$$ax_1 + by_1 + c = 0$$

$$ax_2 + by_2 + c = 0$$



$$(a, b, c) \cdot (x_1, y_1, 1) = 0$$

$$(a, b, c) \cdot (x_2, y_2, 1) = 0$$



$$(a, b, c) = (x_1, y_1, 1) \times (x_2, y_2, 1)$$

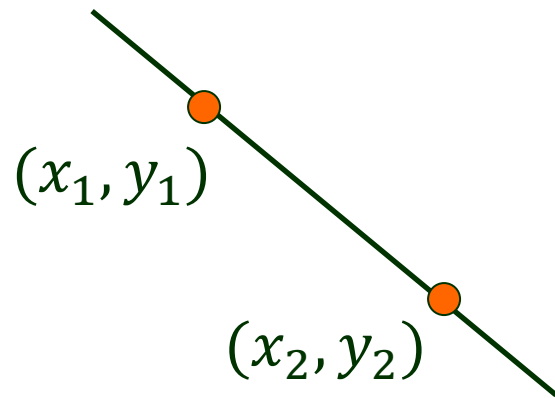
Scaling yields the same line!

Ex. The line through $(3, 1)$ and $(-4, 5)$ has coefficients (i.e., homogeneous coordinates)

$$(3, 1, 1) \times (-4, 5, 1) = (-4, -7, 19)$$

Line through Two Points*

$$ax + by + c = 0?$$



$$ax_1 + by_1 + c = 0$$

$$ax_2 + by_2 + c = 0$$



$$(a, b, c) \cdot (x_1, y_1, 1) = 0$$

$$(a, b, c) \cdot (x_2, y_2, 1) = 0$$



$$(a, b, c) = (x_1, y_1, 1) \times (x_2, y_2, 1)$$

Scaling yields the same line!

Ex. The line through $(3, 1)$ and $(-4, 5)$ has coefficients (i.e., homogeneous coordinates)

$$(3, 1, 1) \times (-4, 5, 1) = (-4, -7, 19) \quad \text{and equation} \quad -4x - 7y + 19 = 0$$

Advantages of Homogeneous Coordinates*

✦ Scaling independent:

$$(25, 23, 17), (50, 46, 34), \left(\frac{25}{17}, \frac{23}{17}, 1\right)$$

all represent the same point $\left(\frac{25}{17}, \frac{23}{17}\right)$

Advantages of Homogeneous Coordinates*

✦ Scaling independent:

$$(25, 23, 17), \quad (50, 46, 34), \quad \left(\frac{25}{17}, \frac{23}{17}, 1\right)$$

all represent the same point $\left(\frac{25}{17}, \frac{23}{17}\right)$

✦ Uniform handling of all cases (horizontal, perpendicular, parallel lines, etc.)

Advantages of Homogeneous Coordinates*

- ✦ Scaling independent:

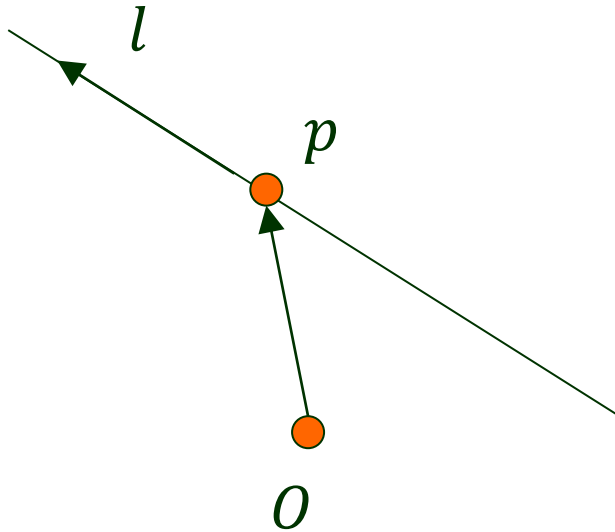
$$(25, 23, 17), (50, 46, 34), \left(\frac{25}{17}, \frac{23}{17}, 1\right)$$

all represent the same point $\left(\frac{25}{17}, \frac{23}{17}\right)$

- ✦ Uniform handling of all cases (horizontal, perpendicular, parallel lines, etc.)
- ✦ No need to solve equations – just take a cross product

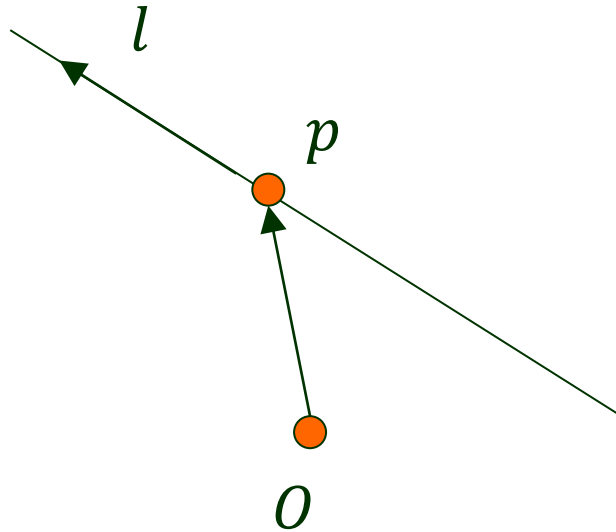
Lines in the Space*

Use Plucker coordinates: $(l, p \times l)$



Lines in the Space*

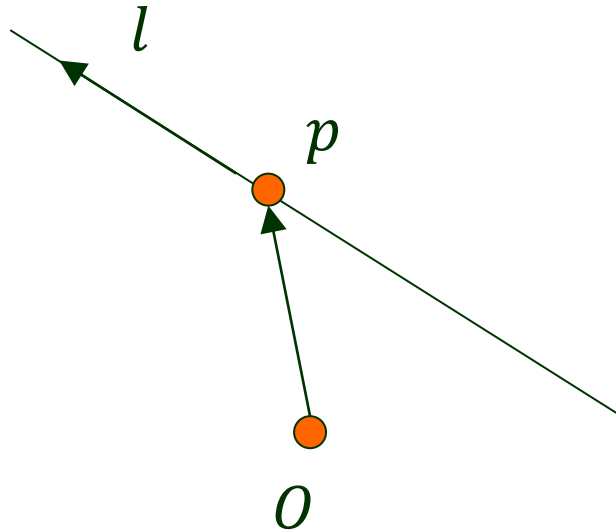
Use Plucker coordinates: $(l, p \times l)$



✱ Compute the distance between two lines.

Lines in the Space*

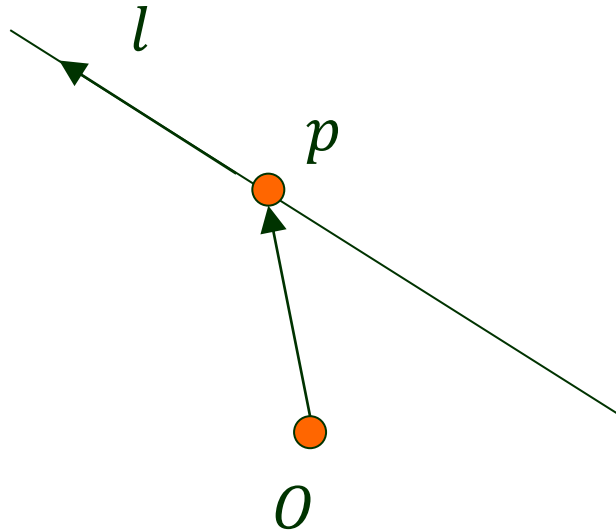
Use Plucker coordinates: $(l, p \times l)$



- ✱ Compute the distance between two lines.
- ✱ Find their common perpendicular.

Lines in the Space*

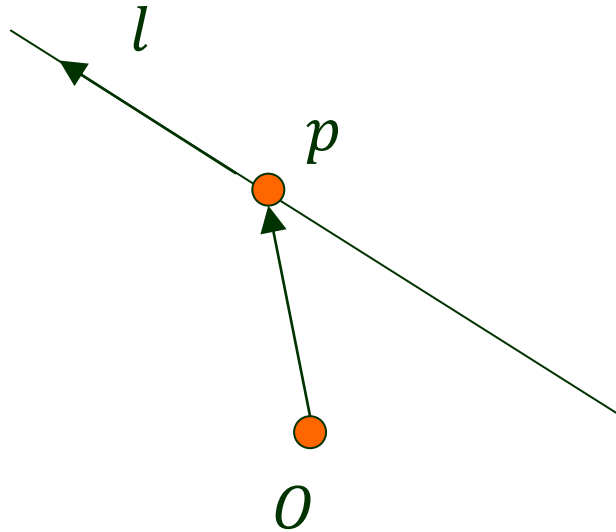
Use Plucker coordinates: $(l, p \times l)$



- ✱ Compute the distance between two lines.
- ✱ Find their common perpendicular.
- ✱ Find intersections with their common perpendicular.

Lines in the Space*

Use Plucker coordinates: $(l, p \times l)$

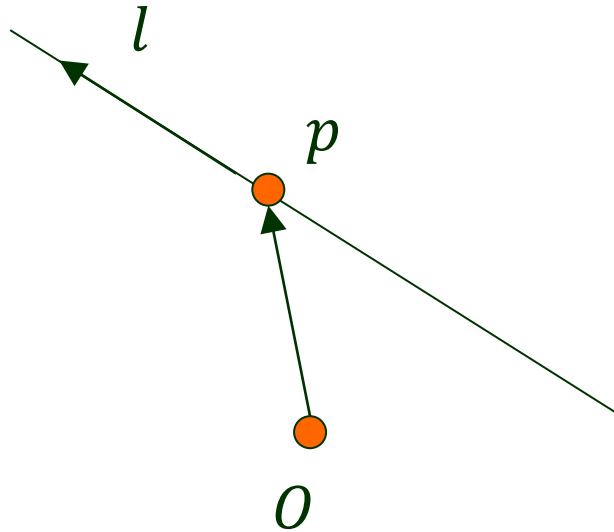


- ✱ Compute the distance between two lines.
- ✱ Find their common perpendicular.
- ✱ Find intersections with their common perpendicular.

(When the lines intersect, the two intersections coincide.)

Lines in the Space*

Use Plucker coordinates: $(l, p \times l)$



- ✱ Compute the distance between two lines.
- ✱ Find their common perpendicular.
- ✱ Find intersections with their common perpendicular.

(When the lines intersect, the two intersections coincide.)